

SERIES: PSA-1100 | **DESCRIPTION:** AC-DC HOT-SWAP POWER SUPPLY

FEATURES

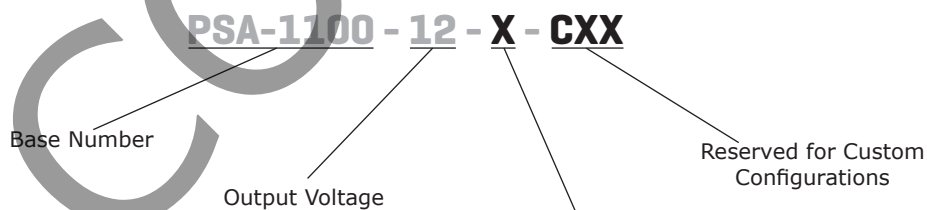
- up to 1100 W continuous power
- high power density - 25.34 W/in³
- slim line 1U form factor
- PMBus™ communication for monitoring and control
- front to back (-F) and back to front (-B) airflow versions
- power factor correction
- 3.3 Vdc or 5 Vdc standby voltage (2 A) options
- redundant (N+1) operation
- blind mate connections for hot-swap
- DROOP current sharing or forced current sharing (optional)
- remote on/off control, power good signal



| MODEL | output voltage | output current | output power | ripple and noise ¹ | efficiency ² |
|--------------------------------|----------------|----------------|--------------|-------------------------------|-------------------------|
| | (Vdc) | max (A) | max (W) | max (mVp-p) | typ (%) |
| PSA-1100-12-F | 12 | 92 | 1100 | 120 | 93.5 |
| PSA-1100-12-B ^{3,4,5} | 12 | 92 | 1100 | 120 | 93.5 |

Notes:

1. Measured at 20 MHz bandwidth at an oscilloscope jack on the output with 0.1 μ F ceramic and two 180 μ F polymer capacitors at a 2" distance from V1 output connector.
2. At 230 Vac input, 550 W.
3. At 100~240 Vac input, maximum of 1100 W at Ta=29°C.
4. At 100~240 Vac input, maximum of 740 W at Ta=50°C.
5. At 200~240 Vac input, maximum of 1100 W at Ta=48°C.
6. All specifications measured at: Ta=25°C and 220 Vac input voltage unless otherwise specified.

PART NUMBER KEY

Airflow Direction:

F = AC input connector to DC output connector
 B = DC output connector to AC input connector

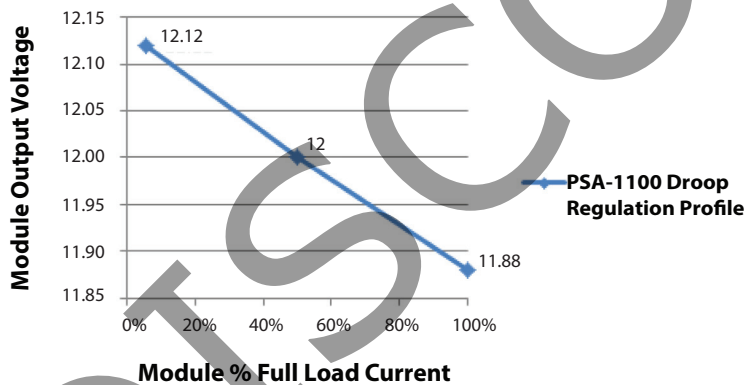
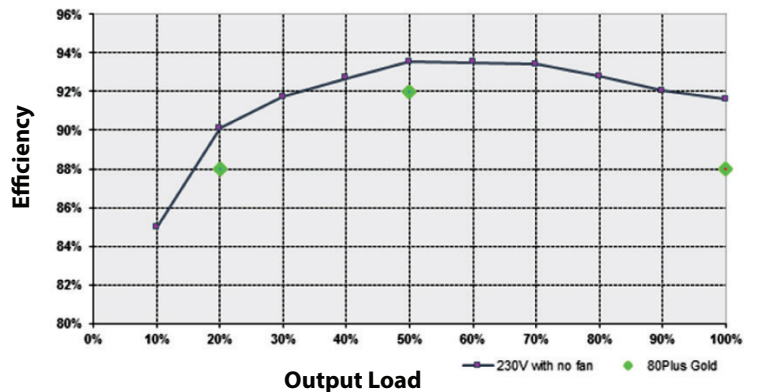
INPUT

| parameter | conditions/description | min | typ | max | units |
|-------------------------|--|------|----------|-------------|--------------|
| voltage | | 90 | | 264 | Vac |
| frequency | | 47 | | 63 | Hz |
| current | at 90 Vac at 180 Vac | | | 14.4 8.0 | Arms Arms |
| inrush current | at 115 Vac, cold start at 230 Vac, cold start | | 20 40 | | A A |
| leakage current | | | | 1.5 | mArms |
| power factor correction | at 115 Vac, full load | 0.95 | | | |

OUTPUT - V1 (MAIN OUTPUT)

| parameter | conditions/description | min | typ | max | units |
|---|---|-----|------|--------|-------|
| line regulation | | | ±1.5 | | % |
| load regulation | | | ±1.5 | | % |
| load capacitance | | | | 30,000 | µF |
| transient response | 25% step load, 1A/µs slew rate, recovery to 1% within 1 ms | | | 5 | % |
| start-up time | | | | 1.5 | s |
| hold-up time | at 230 Vac, full load | 12 | | | ms |
| remote sense | between both output terminals | | 0.3 | | V |
| current share accuracy (Droop) ¹ | over 10% to 100% load | | ±4 | | A |
| LED indicator | AC OK: "green" to indicate AC above the lower limit that is required to sustain normal operation DC OK: "green" to indicate module in normal operating condition | | | | |

Notes: 1. Droop regulation of ±1.0% for an overall combined regulation allowance of ±1.5%

PSA-1100 Droop Regulation Profile**Efficiency vs. Output Current****OUTPUT - V2 (STANDBY OUTPUT)**

| parameter | conditions/description | min | typ | max | units |
|-------------------------------|------------------------|-----|-------|-----|-------|
| output voltage | selectable | | 3.3/5 | | Vdc |
| output current | | 0 | | 2 | A |
| ripple and noise ² | | | | 100 | mVp-p |
| line regulation | | | ±2 | | % |

Notes: 2. Measured at 20 MHz bandwidth at an oscilloscope jack on the output with 100 µF low ESR capacitor at 0.5" from V2 output connector.

OUTPUT - V2 (STANDBY OUTPUT CONTINUED)

| parameter | conditions/description | min | typ | max | units |
|--------------------|--|-----|-----|------|-------|
| load regulation | | | ±2 | | % |
| load capacitance | | | | 2200 | µF |
| transient response | 25% step load, 1A/µs slew rate, recovery to 1% within 1 ms | | | 5 | % |
| start-up time | | | | 1.5 | s |

PROTECTIONS

| parameter | conditions/description | min | typ | max | units |
|-----------------------------|------------------------|-------|-----|-------|-------|
| over voltage protection | V1: latch off | 13.2 | | 14.5 | Vdc |
| | V2: latch off | 110 | | 120 | % |
| over current protection | V1: auto recovery | 101.2 | | 128.8 | A |
| | V2 | | | 3 | A |
| over temperature protection | auto recovery | | 55 | | °C |

SAFETY & COMPLIANCE

| parameter | conditions/description | min | typ | max | units |
|--|--|---------|-----|-----|-------|
| insulation safety rating / test voltage | input to output, reinforced | 3,000 | | | Vrms |
| | input to chassis, basic | 1,500 | | | Vrms |
| isolation voltage | output to chassis | 100 | | | Vrms |
| | V2 to chassis/ground | 100 | | | Vdc |
| grounding | the output signals are referenced to the A2 and B2 return connection | | | | |
| safety approvals | EN60950-1:2006+A11+A1+A12, IEC60950-1:2005+Amd 1, CAN/CSA-C22.2 No.60950-1-07+A1:2011, UL 60950-1:2007 R12.11(NRTL Route), EEC/93/68/LVD, 2006/95/EC LVD | | | | |
| conducted emissions | FCC 15 Sub Part B, EN55022, Class A: tested with resistive load | | | | |
| radiated emissions | FCC 15 Sub Part B, EN55022, Class A: tested with resistive load | | | | |
| harmonic compliance | EN/IEC 61000-3-2:2009, Class A Harmonic Limits Compliance Level: 230 Vac line voltage; 100% output load | | | | |
| flicker | EN/IEC 61000-3-3:2009 limits as specified in the standard: flicker and voltage fluctuations | | | | |
| electrostatic discharge | EN/IEC 61000-4-2, ±8 kV operational air discharge, ±8 kV contact discharge: all parameters to remain within limits, test set up to be defined | | | | |
| RF electro-magnetic field. amplitude modulated | EN/IEC 61000-4-3 80~1000 MHz, 10 V/m, 80% AM Modulation (1 kHz): all parameters to remain within limits, test set up to be defined | | | | |
| immunity to fast transients | EN/IEC 61000-4-4 Power lines: ±2 kV: all parameters to remain within limits, test set up to be defined | | | | |
| surges (mains) | EN/IEC 61000-4-5 ±1kV line to line, ±2 kV line to earth, Criteria A: all parameters to remain within limits, test set up to be defined | | | | |
| RF continuous conducted | EN/IEC 61000-4-6 150 kHz~80 MHz 3Vrms 80% AM (1 kHz), Criteria A: all parameters to remain within limits, test set up to be defined | | | | |
| voltage dips/interruptions | IEC 61000-4-11 30% reduction for 10 ms, 60% reduction for 100 ms: Reset is permitted must be selfrecovering. Additionally, the PSU shall not latch up during any brownout condition. | | | | |
| MTBF | as per Telcordia SR-332, Issue 2, Sept 2006 component stress method at Ta=40°C, full load | 500,000 | | | hours |
| RoHS | 2011/65/EU | | | | |
| WEEE | 2012/19/EU | | | | |

ENVIRONMENTAL

| parameter | conditions/description | min | typ | max | units |
|------------------------------------|--|-----|-----|-----|---------|
| operating temperature ¹ | | 0 | | 50 | °C |
| storage temperature | non-condensing | -40 | | 70 | °C |
| operating humidity | non-condensing | 10 | | 90 | % |
| storage humidity | | 5 | | 90 | % |
| acoustic | ISO 7779-1999 | | | 60 | dB LpAm |
| cold ² | IEC 68 Part 2 – 1: at -10°C minimum for 4 hours | | | | |
| dry heat | IEC 68 Part 2 – 2: at 50°C minimum for 4 hours | | | | |
| damp heat, cyclic | IEC 68 Part 2 – 30: at 20~45°C, 30~95 %RH | | | | |
| low air pressure (operating) | IEC 68 Part 2 – 13: at 10,000 feet, 697 mbar | | | | |
| vibration (sinusoidal) | IEC 68 Part 2 – 6: at 10~58 Hz, 0.075 mm; 58~500 Hz, 10 m/s ² , 1 octave/minute, 10 cycles/ main axis | | 1 | | G |
| shock | IEC 68 Part 2 – 27: at 300 m/s ² , 11 ms, half sine wave 3 shocks/main axis | | 30 | | G |
| bump | IEC 68 Part 2 – 29: at 150 m/s ² , 6 ms, half sine wave 900 bumps/main axis | | 15 | | G |

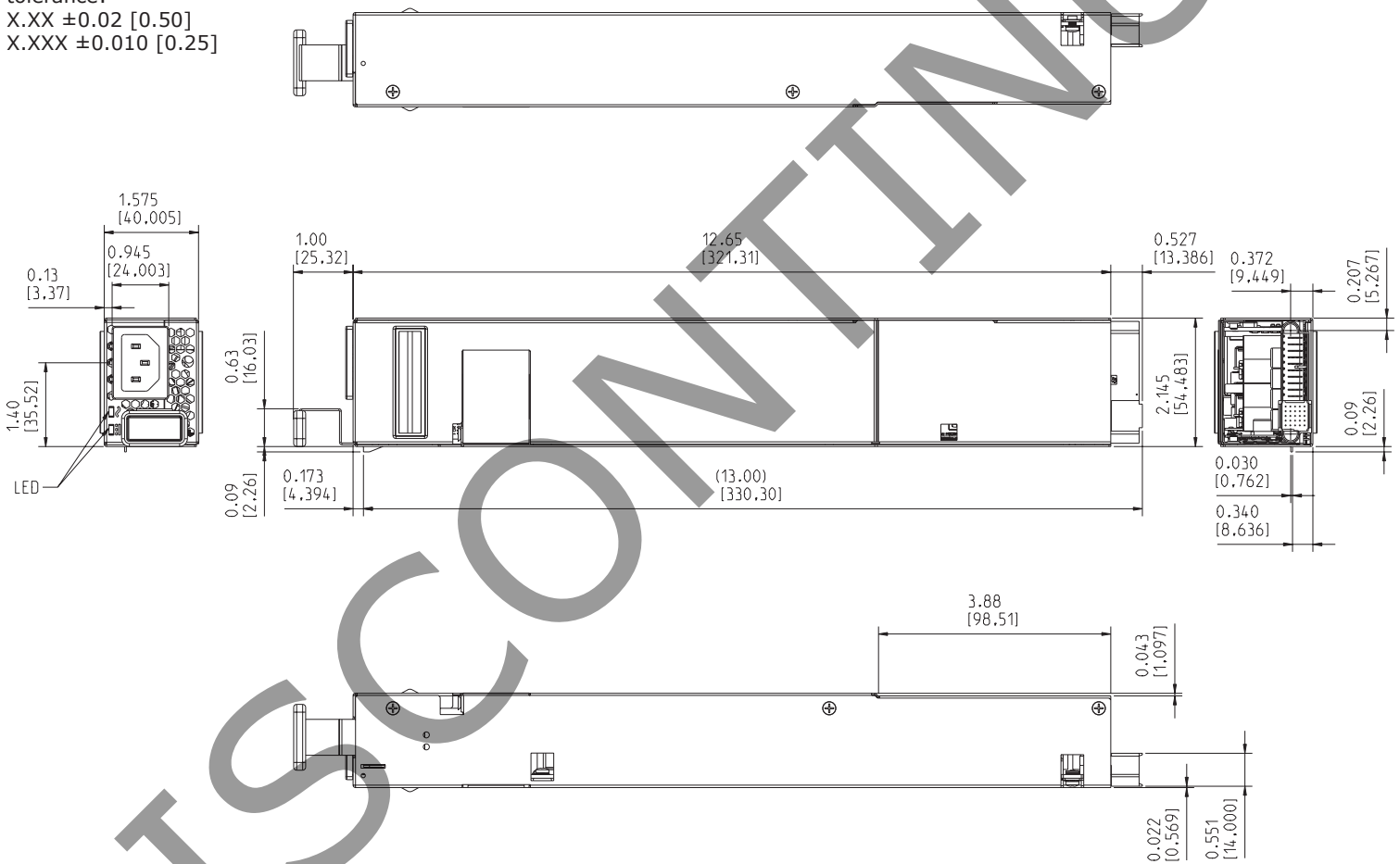
Notes: 1. PSA-1100-12-B: At 100~240 Vac input, maximum of 1100 W at Ta=29°C. At 100~240 Vac input, maximum of 740 W at Ta=50°C. At 200~240 Vac input, maximum of 1100 W at Ta=48°C.
2. The module shall start up at -10°C, however it is not required that the full specification is achieved until the operational internal temperature has risen to 0°C.

MECHANICAL

| parameter | conditions/description | min | typ | max | units |
|-----------------------|---|-----|-----|-----|--------|
| dimensions | 12.65 x 2.145 x 1.575 (321.3 x 54.5 x 40.0 mm) | | | | inches |
| weight | | | 1.1 | | kg |
| cooling / airflow | integral fan | | | | |
| material flammability | UL 94V-0 | | | | |
| AC input | IEC320/C14 | | | | |
| DC output | Tyco Electronics P/N 2-1926734-2 mates with Tyco Electronics P/N 2-1926739-5 | | | | |

MECHANICAL DRAWING

units: inches [mm]
 tolerance:
 X.XX ±0.02 [0.50]
 X.XXX ±0.010 [0.25]



DC OUTPUT PIN ASSIGNMENTS

| PIN | FUNCTION | DESCRIPTION | HIGH / LOW LEVEL | Imax | |
|--------------------|--------------------|---|--|----------------|---------|
| 1,2,3,4,5 | 12 V output return | V1 (-VE) main output return | | | |
| 6,7,8,9,10 | 12 V output | V1 (+VE) main output | | | |
| signal pin row "A" | A1 | Vstandby +VE | positive output of standby (V2) | | |
| | A2 | signal/logic return | common with V1 & V2 returns | | |
| | A3 | I ² C address select | analog I ² C address selection | | |
| | A4 | SCL | communications clock line | | |
| | A5 | PSKILL_H | disables power on extraction (recessed pin) | | |
| | | | pin status | module | |
| | | | open circuit | "off" | |
| logic "1" | | | "off" | | |
| logic "0" | "on" | | | | |
| signal pin row "B" | B1 | Vstandby +VE | positive output of standby (V2) | | |
| | B2 | signal/logic return | common with V1 & V2 Returns | | |
| | B3 | not use | reserved | | |
| | B4 | PS_ON_L (remote_ON_L) | internally pulled up to 3.3 V via 3.01 kΩ if PSKILL_H is connected to return | | |
| | | | open to A2/B2 | short to A2/B2 | |
| | | | "off" | "on" | 1.05 mA |
| B5 | Ishare (optional) | active current sharing bus (recessed pin) | | | |
| signal pin row "C" | C1 | Vstandby +VE | positive output of standby (V2) | | |
| | C2 | not use | reserved | | |
| | C3 | SDA | communications data | | |
| | C4 | SMB_ALERT_L | SMBus interrupt line | | |
| | | | logic "1" | "good" | >2.1 V |
| | logic "0" | "fault" | <0.4 A | -5 mA | |
| C5 | DC_OK_H | DC OK Signal (recessed pin) | | | |
| | | logic "1" | "good" | >2.1 V | |
| | | logic "0" | "fault" | <0.4 A | -5 mA |
| signal pin row "D" | D1 | Vstandby +VE | positive output of standby (V2) | | |
| | D2 | not use | reserved | | |
| | D3 | V1 Vsense (-VE) | V1 negative sense line | | |
| | D4 | not use | reserved | | |
| | D5 | Vstandby_select (V2) | selects the voltage of V2 recessed pin | | |
| open circuit | | | short circuit | | |
| 3.3 V | 5 V | | | | |
| signal pin row "E" | E1 | Vstandby +VE | positive output of standby (V2) | | |
| | E2 | not use | reserved | | |
| | E3 | V1 Vsense (+VE) | V1 positive sense line | | |
| | E4 | AC_OK_H | AC incoming source alarm | | |
| | | | logic "1" | "good" | > 2.1 V |
| | logic "0" | "fault" | < 0.4 A | -5 mA | |
| E5 | PS_present | active low, recessed pin, passive signal to detect presence of module, host to provide pull up resistor connected to V2 to source maximum of 5 mA when module is inserted | | | |

APPLICATION NOTES

Digital Interface

The PSA-1100 is provided with a digital communications interface that is based upon a subset of the SMBus™ & PMBus™ Protocols.

The communication interface is a Two Wire Interface (TWI) using devices hardware compatible with I²C.

The interface is based upon the I²C Protocol developed by Philips Semiconductors (now NXP). Reference to the "I²C Bus Specification and User Manual" UM10204 Rev.03 – 19 June 2007 is recommended.

Slave Addresses

The device is selected by setting the Slave Address (Pin A3) either by an external resistor network or by direct connection to logic "high" or "low". Either method interfaced to the appropriate I/O port of the internal I²C device. Therefore the device can be set to respond to all addresses in the range from binary 1011 0000 to 1011 0110 (where the last bit is for read/write that is always set at "0" for initial addressing).

- Connection of Pin A3 to a logic "low" will provide an address of B0 (1011 0000)
- Connection of Pin A3 to a logic "high" (or leaving open circuit) will provide an address of B6 (1011 0110)

To achieve the full range of four potential address combinations Pin A3 requires to be connected to an external resistor that will create an internal analogue voltage that is interpreted by the internal I²C device to derive the following address combinations:

| Possible Module Slave Address Combinations | | | | | | | | | | |
|--|---------------|-------|-------|-------|-----------------------|-------|-------|-------|-----|-----|
| External Resistor Value (Ohms) | Fixed Address | | | | Variable Address Bits | | | | R/W | HEX |
| | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | | |
| 820 | 1 | 0 | 1 | 1 | 0 | 0 | 0 | 0 | B0 | |
| 2700 | 1 | 0 | 1 | 1 | 0 | 0 | 1 | 0 | B2 | |
| 5600 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | B4 | |
| 8200 | 1 | 0 | 1 | 1 | 0 | 1 | 1 | 0 | B6 | |

APPLICATION NOTES (CONTINUED)

General Information

Refer to the PMBus™/SMBus specification for details on read/write operations when dealing with Byte, Word or Block process calls. Packet Error Correction (PEC) and Address Resolution Protocol (ARP) are not supported. If the PMBus™ master tries to read more bytes than the length of the data selected by the command code, the additional bytes will be sent as 0xFF. The PMBus™ slave device may apply clock stretching by holding the clock line (SCL) low after a command to indicate that it is busy processing data. A master device on the PMBus™ may attempt to continue with the communications but must first wait until the clock line is released. Clock stretching times will vary depending on the data being processed and/or if there are any higher priority events during the response but shall not exceed 25 ms.

PMBus™ COMMAND SUBSET

The following is subset of commands (extracted from the "PMBus Power System Management Protocol Specification; Part II Command Language; Rev 1.2, 6 September 2010") and apply on a per module basis, (although certain commands could be applied "globally"). For a full definition of the individual command refer to the above referenced PMBus™ specification.

Note: Hex Command 88h, 89h, 8Bh, 8Ch divide decimal value by 100.

| Command (HEX) | Command Name | No. of Bytes | Read / Write | Command Description |
|---------------|--------------------|--------------|--------------|--|
| 01h | OPERATION | 1 | W | The OPERATION command is used to turn the unit on & off in conjunction with the CONTROL (short; last make, first make pin). The unit remains in the commanded mode until the command is toggled or the unit removed from its slot; in which case the CONTROL pin is de-asserted and overrules the OPERATION command. |
| 03h | CLEAR_FAULTS | 0 | W | Clear fault data |
| 78h | STATUS_BYTE | 1 | R | Lower byte returned from the STATUS_WORD |
| 79h | STATUS_WORD | 2 | R | The command returns two bytes of data relating to the unit fault condition. CUI may elect to provide a subset of information. |
| 88h | READ_VIN | 2 | R | Provides the measured input voltage of the power module in volts. |
| 89h | READ_IIN | 2 | R | Provides the measured input current of the power module in Amps. |
| 8Bh | READ_VOUT | 2 | R | Provides the measured output voltage of the power module in volts. |
| 8Ch | READ_IOUT | 2 | R | Provides the measured output current of the power module in Amps. |
| 8Dh | READ_TEMPERATURE_1 | 2 | R | This command shall return a select component temperature used by the power module, in degrees Celsius. |
| 8Eh | READ_TEMPERATURE_2 | 2 | R | This command shall return the prevailing internal ambient of the power module, in degrees Celsius. |
| 90h | READ_FAN_SPEED_1 | 2 | R | Provides the measured fan speed in the power module in RPM. |
| 96h | READ_POUT | 2 | R | This command shall return the calculated output being delivered by the power module, in Watts. |
| 97h | READ_PIN | 2 | R | This command shall return the calculated input being drawn by the power module, in Watts. |
| 98h | PMBUS_REVISION | 1 | R | PMBus™ Revision |
| 99h | MFR_ID | 8 | R | The command returns the ASCII string for manufacturer's ID. |
| 9Ah | MFR_MODEL | 12 | R | The command returns the ASCII string manufacturer's model. |
| 9Bh | MFR_REVISION | 2 | R | The command returns the ASCII string manufacturer's revision (example case "01"). |
| 9Dh | MFR_DATE | 4 | R | The command returns the ASCII string manufacturer's date code (example case "0913"). |
| 9Eh | MFR_SERIAL | 8 | R | The command returns manufacturers serial number. |

APPLICATION NOTES (CONTINUED)

PMBus™ Non-Standard Extended Command Subset

| Command (HEX) | Command Name | No. of Bytes | Read / Write | Command Description |
|---------------|------------------|--------------|--------------|--|
| 16h | SOFTWARE VERSION | 4 | R | Read vendor specific firmware revision (ASCII string). Example case "A100" |

Remote On/Off (PMBus™ Operation Command 0x01)

This command can be used to turn the unit on and off via the PMBus™ interface.

If B4 (REMOTE_ENABLE) is HIGH (enabled) then the PMBus™ Remote On/Off function can turn the unit off and on. If B4 (REMOTE_ENABLE) is LOW (disabled) then the PMBus™ Remote On/Off function cannot turn the unit on or off and can be ignored.

The bit encoding of the data byte of the command is as follows.

| Bits [7:6] | Bits [5:4] | Bits [3:2] | Bits [1:0] | Unit State |
|------------|------------|------------|------------|------------|
| 00 | XX | XX | XX | Off |
| 01 | XX | XX | XX | Off |
| 10 | 00 | XX | XX | On |
| 10 | 01 | 01 | XX | On |
| 10 | 01 | 10 | XX | On |
| 10 | 10 | 01 | XX | On |
| 10 | 10 | 10 | XX | On |

If any other bit pattern is received take no action.

If the power supply is turned off by this command then set the OFF bit (6 of the low byte) of the status word to 1. Otherwise set it to 0.

APPLICATION NOTES (CONTINUED)

Status Word

This command is a two byte structure (High and Low bytes). The PMBus™ specification (Table 15) details the structure and content of the word. Note that unsupported bits shall be set to "0"

Status Word (79h); Low Byte

| Byte | Bit # | PMBus™ Bit Name | Definition |
|------|-------|-------------------|--|
| Low | Bit 7 | BUSY | Not Supported |
| | Bit 6 | OFF | Pulse Width Modulator enable status: 1 = PWM disabled 0 = PWM enabled |
| | Bit 5 | VOUT_OV | Output over voltage fault 1 = OVP has occurred 0 = OVP has not occurred |
| | Bit 4 | IOUT_OC | OCP; the unit has entered overload protection. 1= OCP has occurred 0= OCP has not occurred |
| | Bit 3 | VIN_UV | Incoming AC under voltage: 1 = AC is not OK 0 = AC is OK |
| | Bit 2 | TEMPERATURE | Over Temperature fault 1 = OTP has occurred 0 = OTP has not occurred |
| | Bit 1 | CML | Not Supported |
| | Bit 0 | NONE OF THE ABOVE | Not Supported |

Status Word; High Byte

| Byte | Bit # | PMBus™ Bit Name | Definition |
|------|-------|-----------------|---|
| High | Bit 7 | VOUT | Voltage Fault or Warning uVP fault only |
| | Bit 6 | IOUT/POUT | Not Supported |
| | Bit 5 | INPUT | Not Supported |
| | Bit 4 | MFR | Auxiliary Specific Failure |
| | Bit 3 | POWER_GOOD# | Not Supported |
| | Bit 2 | FAN | Fan Failure 1 = Fan has failed 0 = Fan has not failed |
| | Bit 1 | OTHER | Not Supported |
| | Bit 0 | UNKNOWN | Not Supported |

DEMO BOARD

Accessories

| Description | CUI Part Number | Vendor/Part Number |
|--------------------------------------|-----------------|--------------------|
| Demo Board ¹ | 01T-156801-1 | |
| DC Output Mating Connector | 22P-S00065-4 | TEConn 2-1926739-5 |
| I ² C dongle ² | | Microchip DV164122 |
| AC power cord ³ | | Qualtek 312019-01 |

Notes:

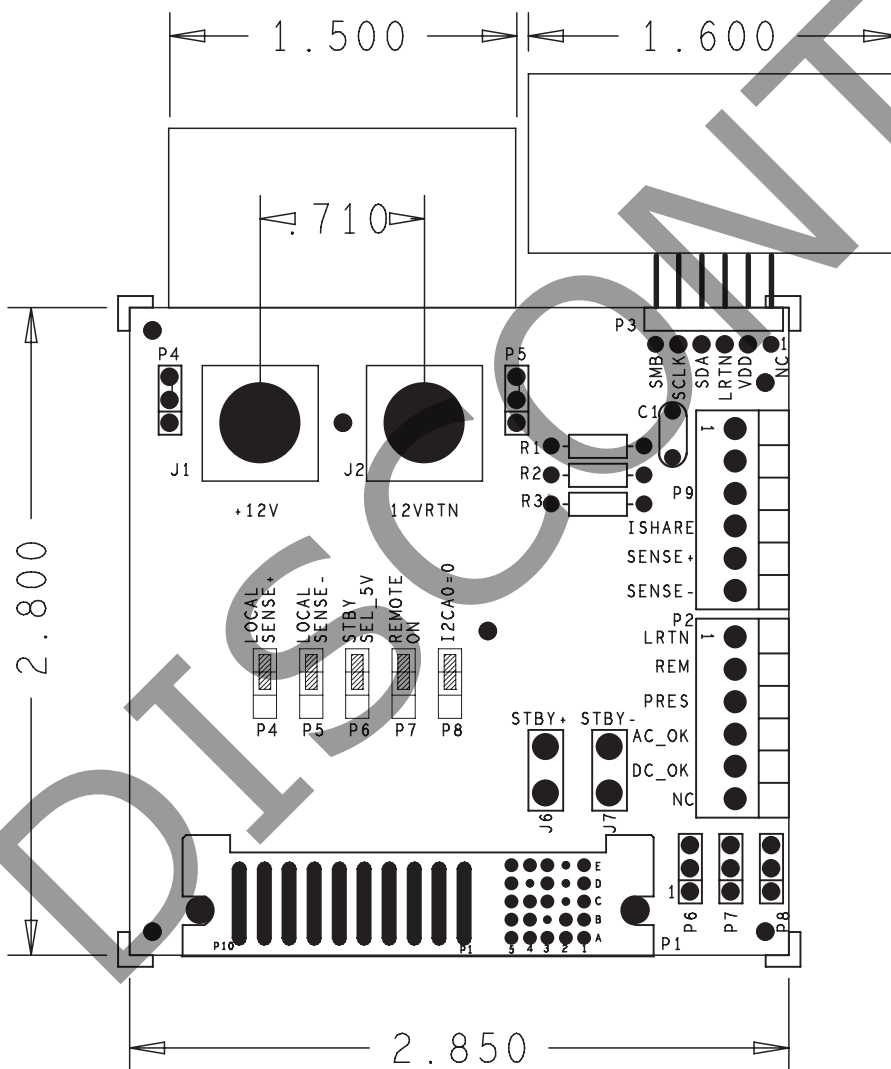
- This demo board is intended for user connection to evaluate the power supply in the laboratory by qualified personnel. Please take necessary safety precautions during product evaluation.
- The PICKit Serial Analyzer is an USB-based tool used to direct communication between a PC and an external serial device. The kit comes complete with hardware (supporting I²C™, SMBus, SPI and USART protocols), an easy-to-use GUI (to configure and display communications) and a target demonstration board for out-of-the-box functionality. http://www.microchip.com/stellent/idcplg?IdcService=SS_GET_PAGE&nodeId=1406&dDocName=en028600
- For North American use only

Demo Board Power Connections

| | |
|----|-----------------------|
| J1 | +12V Output |
| J2 | 12V Return |
| J6 | + Standby Output |
| J7 | Standby Output Return |

Demo Board Connections/Settings

| | |
|----|---|
| P1 | DC Output Mating Connector |
| P2 | Control & Status Signals |
| 1 | Logical Return |
| 2 | Remote ON (override by P7) |
| 3 | Present |
| 4 | AC_OK |
| 5 | DC_OK |
| 6 | NC |
| P3 | I ² C Dongle Connection |
| 1 | SMB |
| 2 | SCL |
| 3 | SDA |
| 4 | Logical Return |
| 5 | VDD |
| 6 | NC |
| P4 | Jumper to Local Sense+, remove jumper for remote sense |
| P5 | Jumper to Local Sense-, remove jumper for remote sense |
| P6 | Jumper to Select 5V Standby, remove jumper to set 3.3V Standby |
| P7 | Jumper to ON, remove jumper for Remote ON/OFF |
| P8 | Jumper to set I ² C A0 = 0, remove jumper to set address by host |
| P9 | Control & Status Signals |
| 1 | NC |
| 2 | NC |
| 3 | NC |
| 4 | ISHARE (optional force sharing) |
| 5 | SENSE+ (override by P4) |
| 6 | SENSE- (override by P5) |



REVISION HISTORY

| rev. | description | date |
|------|------------------------|------------|
| 1.0 | initial release | 05/07/2015 |
| 1.01 | updated datasheet | 07/15/2015 |
| 1.02 | added efficiency curve | 06/03/2016 |

The revision history provided is for informational purposes only and is believed to be accurate.



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CUI offers a two (2) year limited warranty. Complete warranty information is listed on our website.

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CUI products are not authorized or warranted for use as critical components in equipment that requires an extremely high level of reliability. A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.