Built-in Amplifier Photoelectric Sensor (Medium Size)

E3S-A



Be sure to read *Safety Precautions* on page 10.

### **Ordering Information**

#### **Built-in Amplifier Photoelectric Sensors**

Red light Infrared light

Sensing method	Appearance	Connection	Sensing distance		Functions	Мо	del		
Sensing method	Appearance	method	Sell	sing ui	stance		Functions	NPN output	PNP output
								E3S-AT11	E3S-AT31
	Horizontal	Pre-wired					Timer         Turbo           Self Diagnosis         External Diagnosis	E3S-AT21	E3S-AT41
Through-beam	⊲ <u>,</u> ] → [ <u>,</u> ⊳	Connector (M12)			<b>7</b>			E3S-AT16	E3S-AT36
Sensors						m		E3S-AT61	E3S-AT81
	Vertical $\square \rightarrow \square$	Pre-wired					Timer         Turbo           Self Diagnosis         External Diagnosis	E3S-AT71	E3S-AT91
		Connector (M12)						E3S-AT66	E3S-AT86
	Horizontal							E3S-AR11	E3S-AR31
		Pre-wired					Timer         Turbo           Self Diagnosis         External Diagnosis	E3S-AR21	E3S-AR41
Retro-reflective	⊲	Connector (M12)			2 m			E3S-AR16	E3S-AR36
Sensors				(1	00 mm)			E3S-AR61	E3S-AR81
	Vertical Ţ ↔ []	Pre-wired			*1		Timer         Turbo           Self Diagnosis         External Diagnosis	E3S-AR71	E3S-AR91
		Connector (M12)						E3S-AR66	E3S-AR86

Concing mothed	Annosranco	Connection	Concing distance	Functions	Мос	Model	
Sensing method	Appearance	method	Sensing distance	Functions	NPN output	PNP output	
					E3S-AD13 *2	E3S-AD33	
			100 mm (wide view)	Timer Self Diagnosis	E3S-AD23	E3S-AD43	
					E3S-AD11	E3S-AD31	
		Pre-wired	200 mm	Timer Turbo Self Diagnosis	E3S-AD21	E3S-AD41	
	Horizontal				E3S-AD12	E3S-AD32	
	⊲ ↔		700 mm	Timer Turbo Self Diagnosis	E3S-AD22	E3S-AD42	
		Connector (M12)	100 mm (wide view)		E3S-AD18	E3S-AD38	
			200 mm	T T	E3S-AD16	E3S-AD36	
Diffuse-reflective			700 mm		E3S-AD17	E3S-AD37	
Sensors	Vertical				E3S-AD63 *2	E3S-AD83	
			100 mm (wide view)	Timer Self Diagnosis	E3S-AD73	E3S-AD93	
		Pre-wired			E3S-AD61	E3S-AD81	
			200 mm	Timer Turbo Self Diagnosis	E3S-AD71	E3S-AD91	
	<b>□</b> • •				E3S-AD62	E3S-AD82	
			700 mm	Timer Self Diagnosis	E3S-AD72	E3S-AD92	
			100 mm (wide view)		E3S-AD68	E3S-AD88	
		Connector	200 mm		E3S-AD66	E3S-AD86	
		(M12)	700 mm	-	E3S-AD67	E3S-AD87	

\*1. Values in brackets are the minimum required distance between the Sensor and Reflector. \*2. The following models are available with 200-mm sensing distances: E3S-AD14 and E3S-AD64.

#### Accessories (Order Separately)

**Insert-type Long Slit** 

Slit width	Sensing distance	Minimum sensing object (typical)	Model	Quantity	Remarks
$0.5 \text{ mm} \times 11.1 \text{ mm}$	500 mm	0.2-mm dia.		1 of each for Emitter/	Slits can be used with the E3S-
1 mm × 11.1 mm	1.1 m	0.4-mm dia.	E39-S46	Receiver (4 Slits total)	$AT \square \square$ Through-beam
2 mm × 13.6 mm	2.5 m	0.8-mm dia.	200-040	1 of each for Emitter/ Receiver (2 Slits total)	Sensor.→Page 10

#### **Mutual Interference Prevention Filters**

Sensing distance	Model	Quantity	Remarks
2.4 m	E39-E6	2 of each for Emitter/Receiver (4 Filters total)	Can be used with the E3S-AT□□ Through-beam Sensor. → Page 11

#### **Reflectors/Other Accessories**

Name	Sensing distance (typical)	Model	Quantity	Remarks
Reflectors	2 m (100 mm) * (rated value)	E39-R1	1	Provided with E3S-AR Retro-reflective Sensor.
Small Reflectors	1.3 m (100 mm) *	E39-R3	1	
	600 mm (70 mm) *	E39-R4	1	
	450 mm (100 mm) *	E39-RS1	1	
Tape Reflectors	700 mm (100 mm) *	E39-RS2	1	Enables MSR function.
	900 mm (100 mm) *	E39-RS3	1	
Optical Axis Confirmation Reflector		E39-R5	1	Used to check optical axis for the E3S-AT

Note: When using any Reflector other than the provided one, use a sensing distance of approximately 0.7 times the typical value as a guide. \* Values in brackets are the minimum required distance between the Sensor and Reflector.

#### **Mounting Brackets/Other**

Appearance	Model	Quantity	Remarks
C C C C C C C C C C C C C C C C C C C	E39-L69	1	Provided with E3S-A Horizontal Sensors.
0000	E39-L70	1	Provided with E3S-A Vertical Sensors.
the state	E39-L59	1	Provided with E3S-A Vertical Pre-wired Sensors.
50	E39-L81	1	Provided with E3S-A Vertical Connector Sensors.
	E39-L97	1	Protective Cover for Horizontal Sensors Note: When mounting Sensors with Connectors, the Sensor I/O Connector will come into contact with the Bracket. Mount the Sensor with care.
	E39-L98	1	Protective Cover for Vertical Sensors Note: When mounting Sensors with Connectors, the Sensor I/O Connector will be longer. Mount the Sensor with care.
	E39-L60	1	Close Mounting Plate: Provided with E3S-A Connector Sensors.

Note: If a Through-beam Model is used, order two Mounting Brackets, one for the Emitter and one for the Receiver.

#### Sensors I/O Connectors

Model	Quantity	Remarks
E39-G2	1	Provided with product.

#### **Sensors I/O Connectors**

Cable	Appearance	Cable type		Model
	Straight	2 m	- 3-wire	XS2F-D421-DC0-A
Standard	and the second second	5 m		XS2F-D421-GC0-A
Stanuaru	L-shaped	2 m		XS2F-D422-DC0-A
		5 m		XS2F-D422-GC0-A

## **Ratings and Specifications**

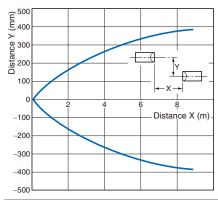
	Sensing method	Through-beam Sensors	Retro-reflective Sensors (with MSR function)		Diffuse-reflective Senso	rs
Item	Model	E3S-AT11, 16, 21, 31, 36, 41, 61, 66, 71, 81, 86, 91	E3S-AR11, 16, 21, 31, 36, 41, 61, 66, 71, 81, 86, 91	E3S-AD13, 18, 23, 33, 38, 43, 63, 68, 73, 83, 88, 93	38, 43, 63, 68, 73, 83, 36, 41, 61, 66, 71, 81,	
Sensing distance 7 m		7 m	2 m (100 mm) *1 (When using E39-R1)	100 mm (wide view) (white paper 100 × 100 mm)	10 to 200 mm (white paper 100 × 100 mm)	700 mm (white paper 200 × 200 mm)
Standard sen	sing object	Opaque: 10-mm dia. min.	Opaque: 75-mm dia. min.			
Differential tra	avel			20% max. of sensing distance	10% max. of sensing distance	20% max. of sensing distance
Directional ar	ngle	Both Emitter and Receiver: 3° to 15°	3 to 10°			
Light source	(wavelength)	Red LED (700 nm)		Infrared LED (880 nm)	Red LED (700 nm)	Infrared LED (880 nm)
Power supply	voltage	10 to 30 VDC, including r	ipple (p-p) 10%			
Current const	umption	Both Emitter and Receiver: 20 mA max. (plus approx. 15 mA with turbo function)	30 mA max. (plus approx. 15 mA with turbo function)	35 mA max.	30 mA max. (plus approx. 15 mA with turbo function)	35 mA max.
Control outpu	ıt		ge: 30 VDC max., Load cu			
Self-diagnost	ic output (Only ith self-diagnos-	(Only Sensors with self-d Load current: 50 mA max Open-collector output (NR	PN or PNP depending on iagnostic function) Load p (residual voltage: 1 V ma PN or PNP depending on	ower supply voltage: 30 V ax.),		
External diagnostic input (Only on Sensors with external diagnostic outputs)	Input voltage	NPN with Emitter OFF: 0 V sho (source current: 1 mA ma with Emitter ON: Open (leakage current: 0.1 mA PNP with Emitter OFF: +DC sh max. (sink current: 3 mA with Emitter ON: Open (leakage current: 0.1 mA	ux.) max.) nort-circuit or −1.5 VDC max.)	) ax.) rt-circuit or –1.5 VDC ax.)		
	Response time	0.5 ms max.				
Protection circuits Power supply reverse polarity protection, Output short-circuit protection			Power supply reverse po	larity protection, Output sl	nort-circuit protection, Mut	ual interference prevention
Response tim	e	Operation or reset: 0.5 m	s max.			
Sensitivity ad	justment	Two-turn endless adjuste	r with an indicator			
	n (Only on Sen- timer function)	0 to 100 ms OFF-delay v	ariable adjuster			_
	n (Only on Sen- turbo function)	Yes (with turbo switch)				
Ambient illum er side)	nination (Receiv-	Incandescent lamp: 5,000 Sunlight: 10,000 lx max.	) lx max.			
Ambient temp	perature		C (with no icing or condense with no icing or condensel			
Ambient hum	<u> </u>	Operating: 35% to 85% (v Storage: 35% to 95% (vit	th no condensation)			
Insulation res			petween current-carrying p			
Dielectric stre	•	1,000 VAC, 50/60 Hz for	1 min. between current-ca	rrying parts and case		
Vibration resi (destruction)	stance	10 to 55 Hz, 1.5-mm doul	ble amplitude for 2 hours e	each in X, Y, and Z direction	ons	
Shock resista (destruction)	ince		mes each in X, Y, and Z d	lirections		
Degree of protection IEC IP67; NEMA: 4X (indoors only) *2						
Connection method Pre-wired (standard length: 2 m) or M12 connector						
Weight (pack	ed state)	Pre-wired cable: Pre-wired cable: Pre-wired cable: Approx 90 g				
	Case	РВТ				
Material	Lens	Denatured polyallylate				
	Mounting Bracket	Stainless steel (SUS304)				
Accessories			crews), Sensitivity adjustmonectors), and Reflector (	ent driver, Sensitivity adju only for Retro-reflective Se	•	eet, Close mounting plate

\*1. Values in brackets are the minimum required distance between the Sensor and Reflector. \*2. National Electrical Manufacturers Association

## Engineering Data (Typical)

#### Parallel Sensing Range

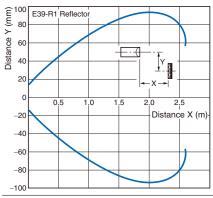
Through-beam Sensors E3S-AT



Parallel Sensing Range

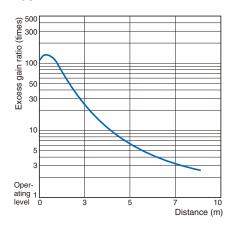
Retro-reflective Sensors

#### E3S-AR - + E39-R1 (with Reflector)



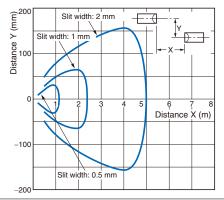
#### Excess Gain vs. Set Distance

## Through-beam Sensors E3S-AT

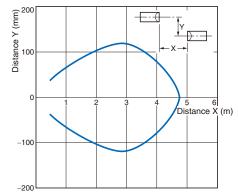


**Through-beam Sensors** 

E3S-AT + E39-S46 (Slit Sold Separately)



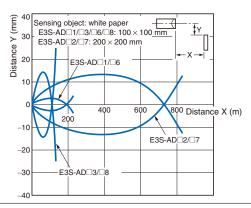
Through-beam Sensors E3S-AT + E39-E6 (Filter Sold Separately)



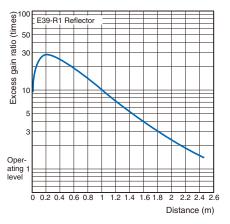
#### Sensing Range

#### **Diffuse-reflective Sensors**

E3S-AD 1/AD 2/AD 3/AD 6/AD 7/AD 8



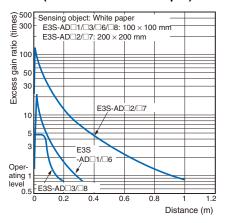
#### Retro-reflective Sensors E3S-AR + E39-R1 (with Reflector)



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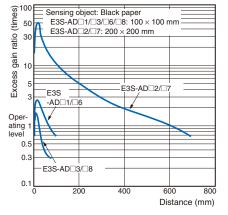
#### **Diffuse-reflective Sensor**

#### E3S-AD 1/AD 2/AD 3/AD 6/AD 7/ AD 8 (Detection of White Paper)



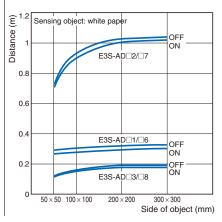
#### **Diffuse-reflective Sensor**

E3S-AD 1/AD 2/AD 3/AD 6/AD 7/ AD 8 (Detection of Black Paper)



## Sensing Object Size vs. Sensing Distance

#### E3S-AD 1/AD 2/AD 3/AD 6/AD 7/ AD 8



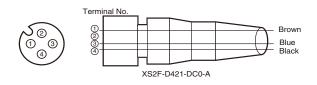
## I/O Circuit Diagrams

#### **NPN Output**

Model	Operation mode	Timing charts	Mode selector switch	Output circuit
E3S-AT11 E3S-AT16 E3S-AT61 E3S-AT66 E3S-AR11 E3S-AR16	Light-ON	Incident light No incident light Light indicator ON (red) OFF Output ON transistor OFF Load Operate (e.g., relay) Reset (Between brown and black)	L Side (LIGHT ON)	Through-beam Receivers, Retro-reflective Sensors, Diffuse-reflective Sensors
E3S-AR61 E3S-AR66 E3S-AD11 E3S-AD16 E3S-AD61 E3S-AD66 E3S-AD12	Dark-ON	Incident light No incident light Light indicator ON (red) OFF Output ON transistor OFF Load Operate (e.g., relay) Reset (Between brown and black)	D Side (DARK ON)	Connector Pin Arrangement
E3S-AD17 E3S-AD62 E3S-AD67 E3S-AD13 E3S-AD18 E3S-AD63 E3S-AD68	Through-be	am Emitters	Brown Brown Blue 3+	10 to       Image: Connector Pin Arrangement         10 to       Image: Connector Pin Arrangement         30 VDC       Image: Connector Pin Arrangement         Note: Pins 2 and 4 are not used.

Model	Operation mode	Timing charts	Mode selector switch	Output circuit
	Light-ON	Incident light No incident light Light indicator ON (red) OFF Output ON transistor OFF Load Operate (e.g., relay) Reset (Between brown and black) T: OFF-delay timer (0 to 100 ms)	L Side (LIGHT ON)	Through-beam Receivers, Diffuse-reflective Sensors
E3S-AT21 E3S-AT71 E3S-AD21 E3S-AD71 E3S-AD22 E3S-AD72 E3S-AD72	Dark-ON	Incident light No incident light Light indicator ON (red) OFF Output ON transistor OFF Load Operate (e.g., relay) Reset (Between brown and black) T: OFF-delay timer (0 to 100 ms)	D Side (DARK ON)	Lincuit Lincuit Lincuit Zo Blue
E3S-AD23 E3S-AD73		External diagnostic input Emitter LED OFF Indicator (red) OF OFF		Through-beam Emitters
E3S-AR21	Light-ON	Incident light No incident light Light indicator ON (red) OFF Output ON transistor OFF Load Operate (e.g., relay) Reset (Between brown and black) T: OFF-delay timer (0 to 100 ms)	L Side (LIGHT ON)	Retro-reflective Sensors
E3S-AR71	Dark-ON	Incident light No incident light Light indicator ON (red) OFF Output ON transistor OFF Load Operate (e.g., relay) Reset (Between brown and black) T: OFF-delay timer (0 to 100 ms)	D Side (DARK ON)	Control to the second s

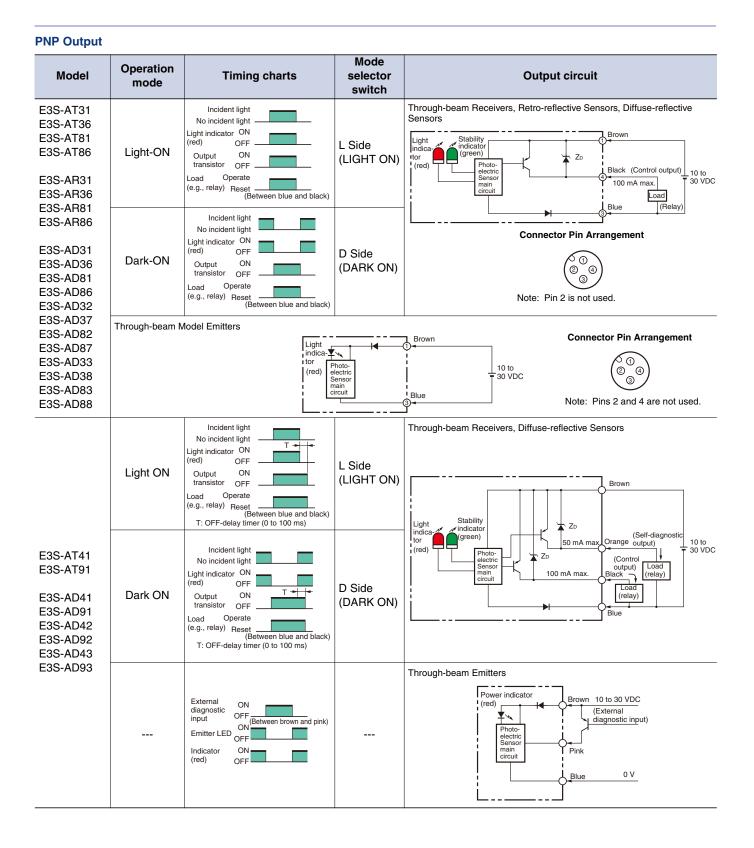
#### Structure of Sensor I/O Connector



Classification	Wire color	Connection Pin No.	Application
	Brown	1	+V
For DC		2	
TOTEC	Blue	3	0 V
	Black	4	Output

Note: Pin No. 2 is not used.

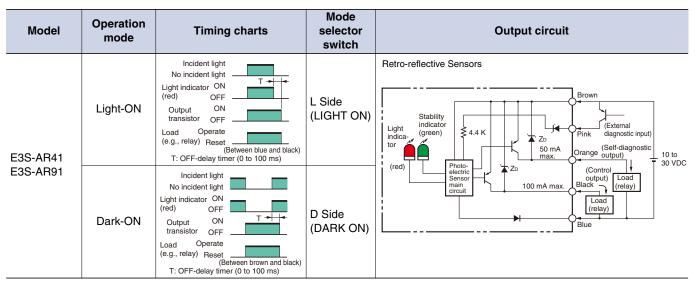




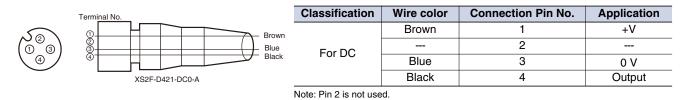
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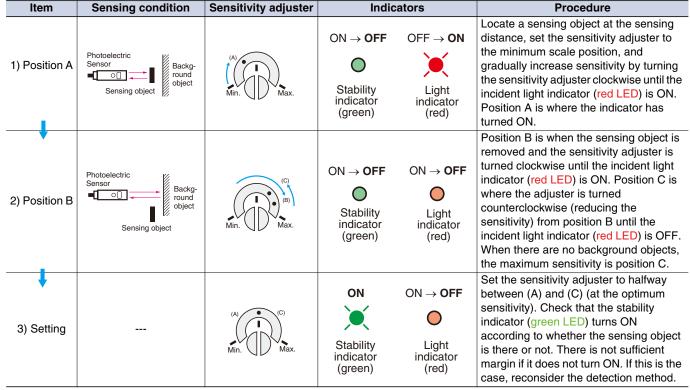


Structure of Sensor I/O Connector



## **Adjustment Methods**

Sensitivity Adjustment for Diffuse-reflective Sensors Set to Light ON



Unlike conventional Photoelectric Sensors, the variation in the sensitivity of E3S-A Photoelectric Sensors is minimal. This means the sensitivity can be adjusted on only a single Photoelectric Sensor, and then <u>the adjusters on the other Photoelectric Sensors</u> can be set to the same scale position. There is no need to adjust the sensitivity of each Photoelectric Sensor individually.

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#### 🔥 WARNING

This product is not designed or rated for ensuring safety of persons. Do not use it for such purposes.



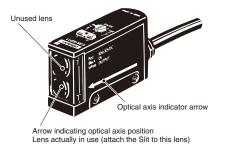
#### **Precautions for Correct Use**

Do not use the product in atmospheres or environments that exceed product ratings.

#### Mounting

#### Position of Optical Axis of Through-beam Model

Unlike conventional through-beam sensors, the E3S-A Through-beam Photoelectric Sensor incorporates 2 lenses. The lens actually in use is the one marked with an arrow indicating the position of the optical axis. When using a Slit, attach it to the lens marked with the arrow.

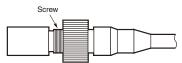


#### **Position of Arrow Indicating Optical Axis**

Model	Position of lens in use	
E3S-A	Top	
(Vertical Sensors)	Тор	
E3S-A		
(Horizontal	Bottom	
Sensors)		

#### **Tightening the Connector**

Manually tighten the connector until the threads have completely disappeared. If tightening is insufficient, the degree of protection may not be maintained, or the connector may become loose when it is subjected to vibration. <u>Using</u> pliers to tighten the connector may damage it.

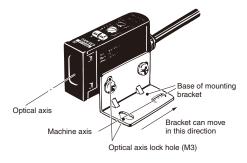


Use the E39-L60 Close Mounting Plate (provided) if the Sensor is mounted using mounting brackets or if it is mounted directly. (Refer to *Dimensions*.)

#### **Mounting Bracket (Provided)**

The direction of the optical axis coincides with the machine axis of the E3S-A when the mounting screw is inserted into the lock hole of the Mounting Bracket. If the mounting surface and the screw hole are correctly aligned toward the sensing object (or toward the Retroreflector for a Through-beam Sensor), the mechanical axis and optical axis will be aligned when the screw is inserted into the hole. Incident light will be detected, and time-consuming adjustment will not be necessary. (If, however, the mounting surface is not flat, adjustment of the optical axis may still be required.) Adjust the position of the Sensor so that incident light points at the center. Make sure that the incident light is at a fixed position.

The maximum tightening torque of the screw is 0.53 N.m max.

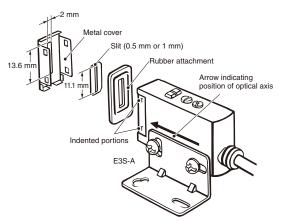


#### Adjustments

#### E39-S46 Through-beam Slits

(Accessory, order separately)

Use the rubber attachment with the metal cover if a slit width of 2 mm is required. (A Slit is not required in this case.) Insert the 0.5- or 1-mm Slit between the metal cover and rubber attachment if a slit width of 0.5 or 1 mm is desired. These Slits fit into the rubber attachment.



Apply the Slit to the lens of the Photoelectric Sensor marked with an arrow indicating the position of the optical axis (apply it to the bottom lens of Horizontal Sensors and the top lens of Vertical Sensors).

#### E39-E6 Polarized Mutual Interference Prevention Filters for Through-beam Sensors

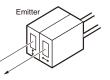
#### (Accessory, order separately)

1

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Receive

- A set of 4 Filters are sold together for two Through-beam Sensors (for 2 each for Emitters and Receivers). Order one for every two sets of Photoelectric Sensors.
- For mounting, refer to the figure of the Through-beam Slits.



Up to two units can be attached

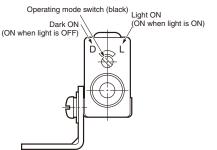
Note: The arrows on the Filters can be attached in either direction when two Sensors are mounted next to each other. The Filter attached to an Emitter and to the corresponding Receiver must be the same in direction of polarization or the Sensor will not function

• The arrow printed on the cover indicates the direction of polarization. By attaching the Filters opposite to each other in polarization to the Emitters and the Receivers in rows, mutual interference can be prevented (in any case, the Filter attached to an Emitter and to the corresponding Receiver must be the same in direction of polarization or the Photoelectric Sensor will not function).

#### **Operating Mode Selection**

As shown in the following illustration, the E3S-A has an operating mode selector on the panel where the Receiver connector is located.

With this operating mode selector, the E3S-A is in either Dark-ON or Light-ON mode.



The default operating mode is shown in the following table.

Sensing method	Default switch setting
Through-beam Sensors Retro-reflective Sensors	Dark-ON
Diffuse-reflective Sensors	Light-ON

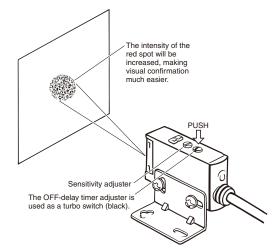
#### Timer and Turbo Switch

The Emitter of the Through-beam Sensor with the selfdiagnostic feature incorporates a turbo switch. When this switch is ON, the intensity of the red LED light source can be increased to make a brighter spot.

#### (Turbo) Function ( Turbo) Switch)

The turbo function is effective with the turbo switch pressed, and the function is reset automatically when released. With the turbo function switched ON, the light spot is visible even at a distance of 200 mm, making it easy to check the sensing position and the angle of the optical axis. Precautions

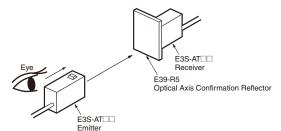
- (1)Do not keep the turbo switch pressed for longer than 3 minutes. (It will not break even if it is pressed for an extended period.)
- (2)Pressing the switch may change the timer delay settings. Set the timer after using the turbo function to check the optical axis.
- (3)To press the switch, use a force of 9.8 N max.



#### Using the E39-R5 Optical Axis Reflector for Throughbeam Sensors

(Accessory, order Separately)

Use this attachment when the set distance is long and adjustment is mechanically difficult with a sensing object.



- Attach the Reflector to the Receiver.
- Look at the Reflector from right behind the Emitter. The Reflector should be bright with red light when the optical beam strikes the Reflector. If the Emitter has a turbo function, the Reflector looks brighter with the function switched ON.
- When the Reflector is removed, the light beam strikes the Receiver.

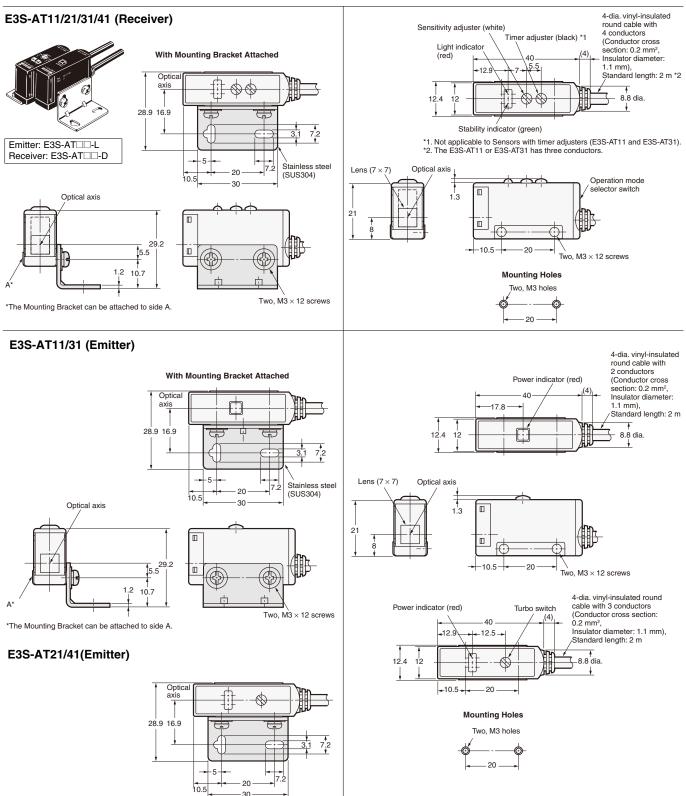
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#### Dimensions

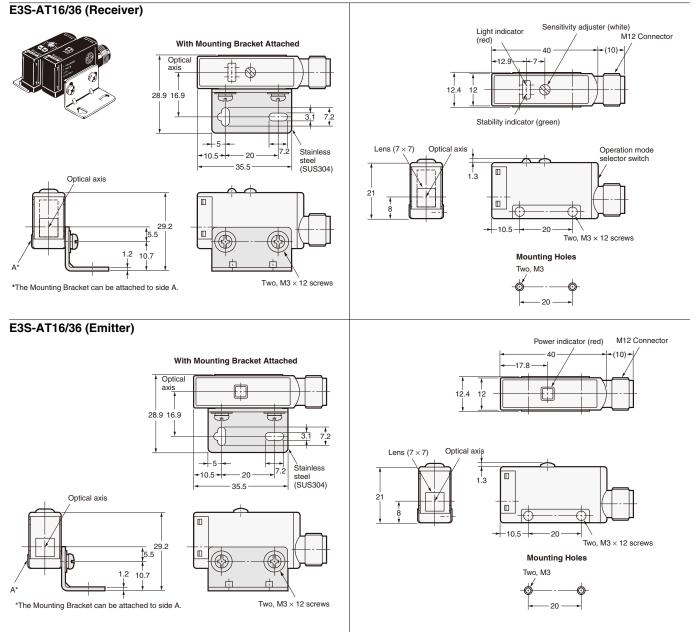
#### E3S-A Built-in Amplifier Photoelectric Sensor

#### **Through-beam Sensors (Horizontal)**

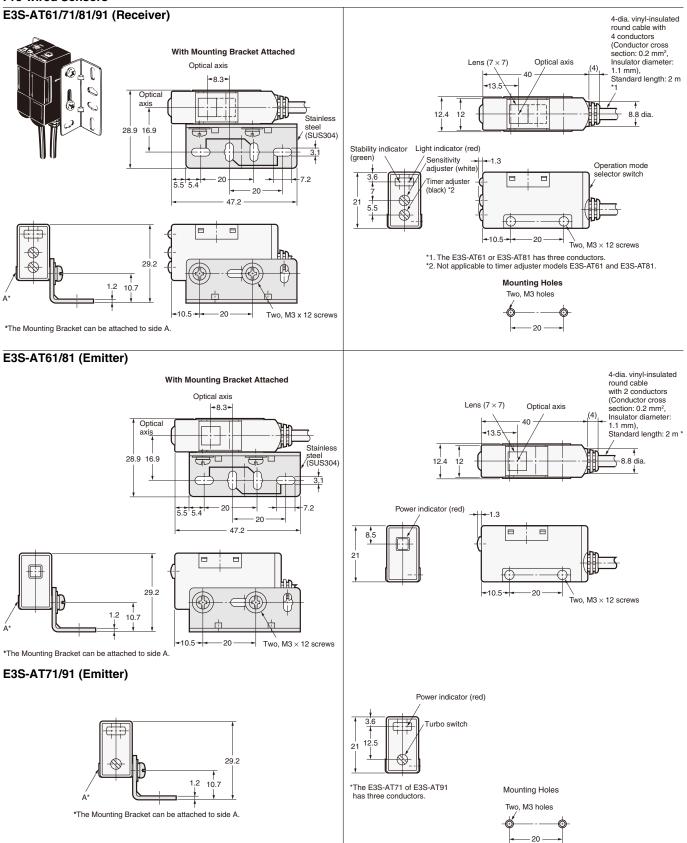
**Pre-wired Sensors** 



## Sensors with Standard Connectors



#### Through-beam Sensors (Vertical) Pre-wired Sensors



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M12 Connector

(10)+

Operation

mode selector

switch

Two, M3 × 12 screws

Lens (7 × 7)

12

Light indicator (red)

3.6

4

è

Sensitivity adjuster (white)

<del>-</del>13.5

-1.3

+10.5-

V

Optical axis 40

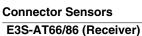
20

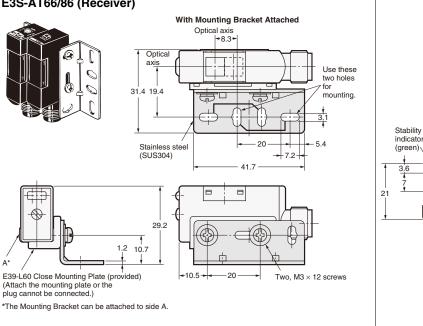
Mounting Holes

20

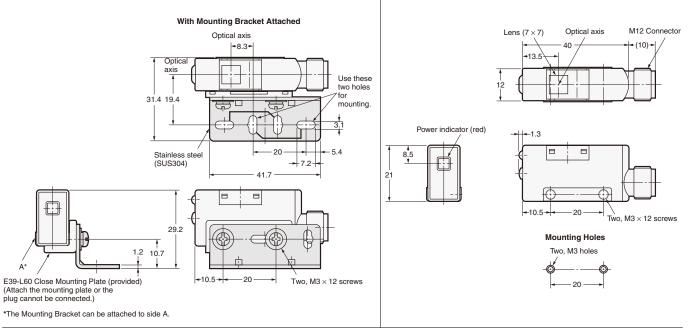
Two, M3 holes

6



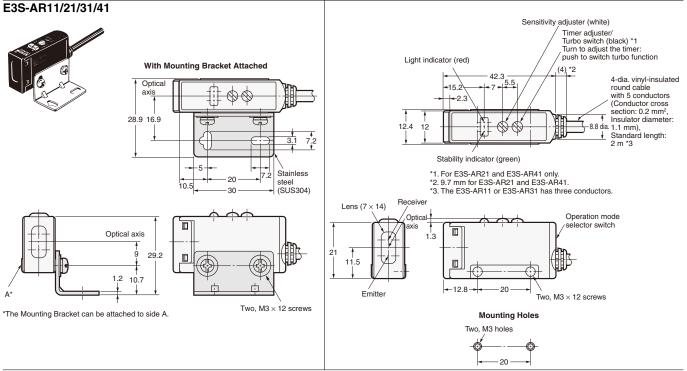


#### E3S-AT66/86 (Emitter)

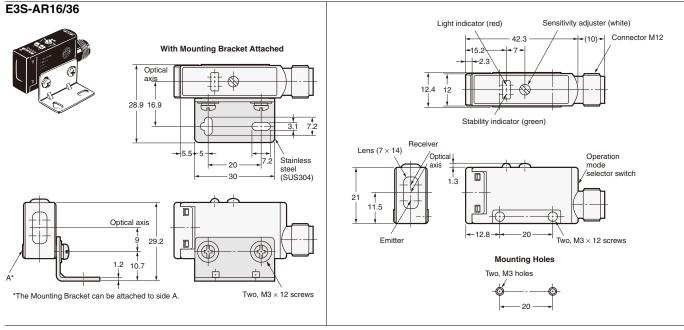


## Retro-reflective Sensors (Horizontal)

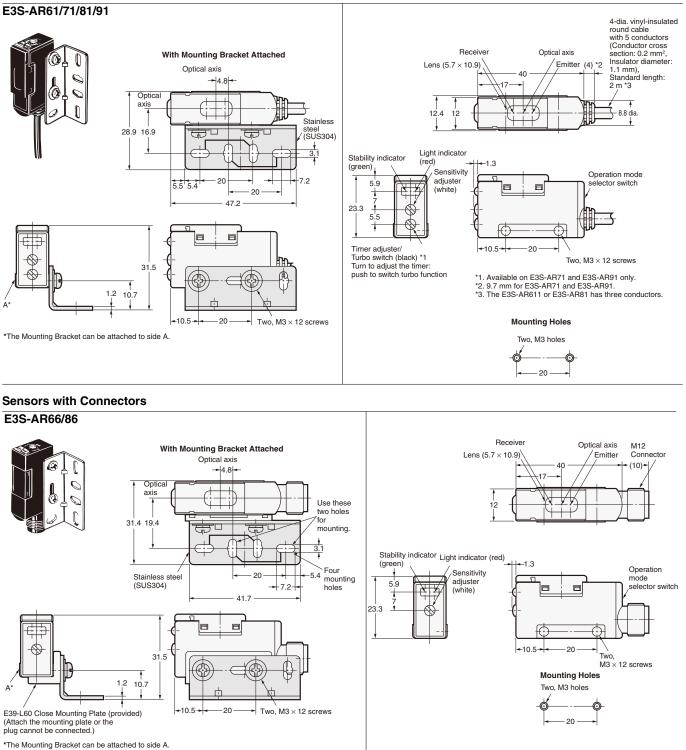
#### Pre-wired Sensors



#### Sensors with Connectors



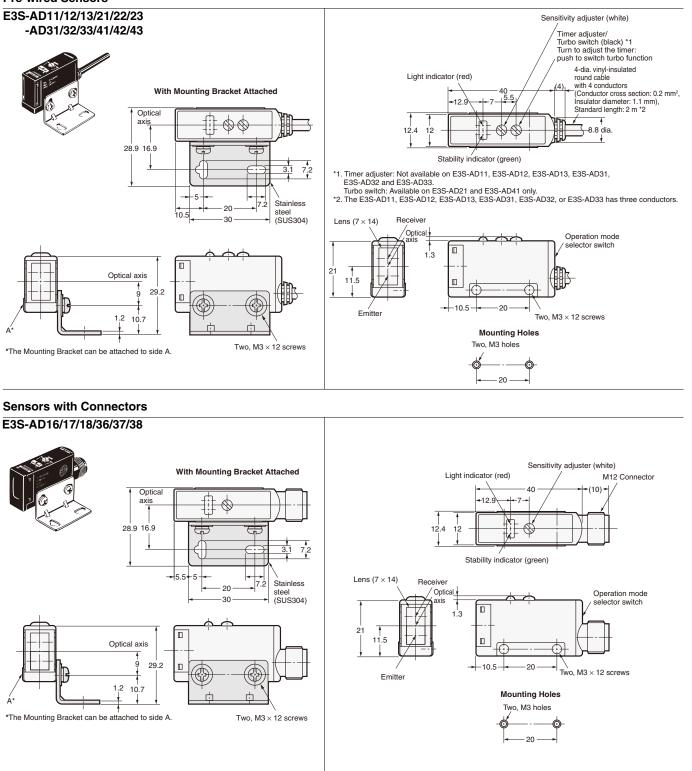
#### Retro-reflective Sensors (Vertical) Pre-wired Sensors



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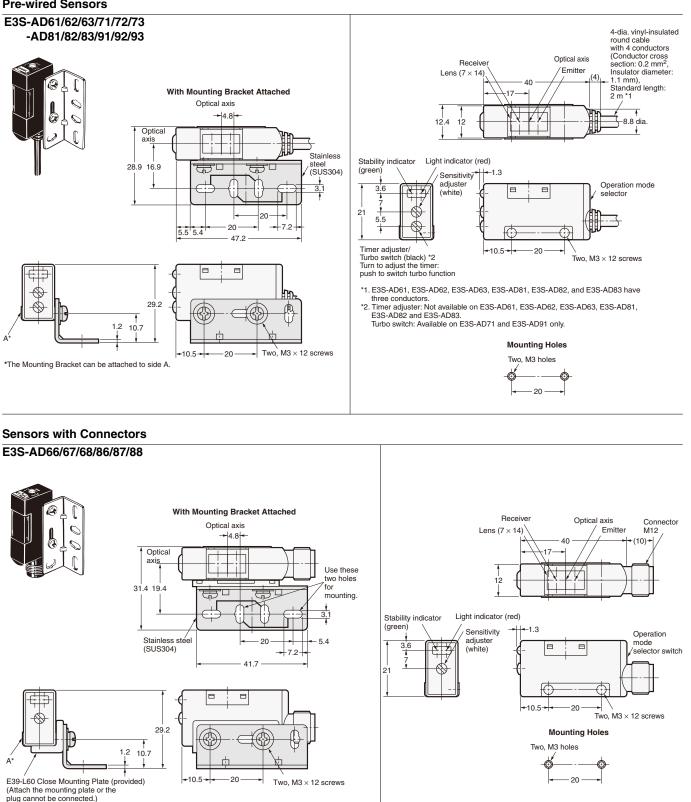
#### Diffuse-reflective Sensors (Horizontal)

#### **Pre-wired Sensors**



#### **Diffuse-reflective Sensors (Vertical)**

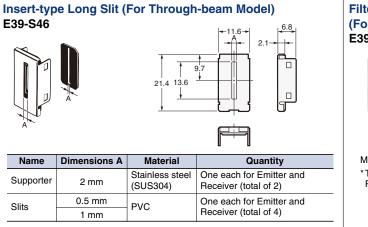
#### **Pre-wired Sensors**



\*The Mounting Bracket can be attached to side A

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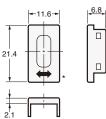
#### Accessories (Order Separately)



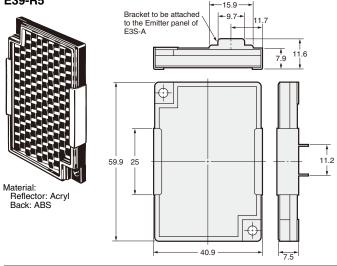
#### Filters for Mutual Interference Prevention (For Through-beam Model) E39-E6



Material: Stainless steel (SUS304) \*Two of each for the Emitter and Receiver (total of four)



#### Optical Axis Confirmation Reflector (For Through-beam Model) E39-R5



#### Reflectors Mounting Brackets

## **Photoelectric Sensors Technical Guide**

#### **General Precautions**

For precautions on individual products, refer to Safety Precautions in individual product information.



presses or other safety devices used to protect human life. These Sensors are designed for use in applications for sensing workpieces and workers that do not affect safety.

# $\bigcirc$

#### Precautions for Safe Use

To ensure safety, always observe the following precautions.

#### Wiring

Item	Typical examples	
Power Supply Voltage Do not use a voltage in excess of the operating voltage range. Applying a voltage in excess of the operating voltage range, or applying AC power (100 VAC or greater) to a DC Sensor may cause explosion or burning.	DC Three-wire NPN Output Sensors	
Load Short-circuiting Do not short-circuit the load. Doing so may cause explo- sion or burning.	• DC Three-wire NPN Output Sensor	• AC Two-wire Sensors Example: E3E2 (Load short circuit) Sensor Blue
Incorrect Wiring Do not reverse the power supply polarity or otherwise wire incorrectly. Doing so may cause explosion or burning.	DC Three-wire NPN Output Sensors Example: Incorrect Polarity	DC Three-wire NPN Output Sensors Example: Incorrect Polarity Wiring      Load     Sensor     Brown     Black     Black
Connection without a load If the power supply is connected directly without a load, the internal elements may burst or burn. Be sure to insert a load when connecting the power supply.	DC Three-wire NPN Output Sensors      Brown 12 to 24VDC Black OV Blue OV	AC 2-wire Sensors Example: E3E2 etc.      Brown     Sensor     Blue

#### • Operating Environment

(1) Do not use a Sensor in an environment where there are explosive or inflammable gases.

(2) Do not use the Sensor in environments where the cables may become immersed in oil or other liquids or where liquids may penetrate the Sensor. Doing so may result in damage from burning and fire, particularly if the liquid is flammable.

#### **Precautions for Correct Use**

#### Design

#### **Power Reset Time**

**Mutual Interference** 

The Sensor will be ready to detect within approximately 100 ms after the power is turned ON.

If the Sensor and the load are connected to separate power supplies, turn ON the Sensor power before turning ON the load power. Any exceptions to this rule are indicated in *Safety Precautions* in individual product information.

#### **Turning OFF Power**

An output pulse may be generated when the power is turned OFF. It is recommended that the load or load line power be turned OFF before the Sensor power is turned OFF.

#### **Power Supply Types**

An unsmoothed full-wave or half-wave rectifying power supply cannot be used.

Mutual interference is a state where an output is unstable because the Sensors are affected by light from the adjacent Sensors. The following measures can be taken to avoid mutual interference.

Counter- measure	Concept	Through-beam Sensors	Reflective Sensors
1	Use a Sensor with the interference prevention function.	If Sensors are mounted in close proximity, use Sensors with the interference prevention function. 10 or fewer Sensors: E3X-DA	
2	Install an inference prevention filter.	A mutual interference prevention polarizing filter can be installed on only the E3Z-TA to allow close-proximity mounting of up to 2 Sensors. Mutual Interference Prevention Polarizing Filter: E39-E11	
3	Separate Sensors to distance where interference does not occur.	Check the parallel movement distance range in the catalog, verify the set distance between adjacent Sensors, and install the Sensors accordingly at a distance at least 1.5 times the parallel movement distance range.	If the workpieces move from far to near, chattering may occur in the vicinity of the operating point. For this type of application, separate the Sensors by at least 1.5 times the operating range. $1.5 \times L$ Workpiece Sensor
4	Alternate Emitters and Receivers.	Close mounting of Sensors is possible by alternating the Emitters with the Receivers in a zigzag fashion (up to two Sensors). However, if the workpieces are close to the Photoelectric Sensors, light from the adjacent Emitter may be received and cause the Sensor to change to the incident light state.	
5	Offset the optical axes.	If there is a possibility that light from another Sensor may enter the Receiver, change the position of the Emitter and Receiver, place a light barrier between the Sensors, or take other measures to prevent the light from entering the Receiver. (Light may enter even if the Sensors are separated by more than the sensing distance.)	If Sensors are mounted in opposite each other, slant the Sensors as shown in the following diagram. (This is because the Sensors may affect each other and cause output chattering even if separated by more than the Sensor sensing distance.) Sensor $\theta$
6	Adjust the sensitivity.	Lowering the sensitivity will generally help.	

#### Noise

Countermeasures for noise depend on the path of noise entry, frequency components, and wave heights. Typical measures are as given in the following table.

Type of noise	Noise intrusion path and countermeasure	
Type of noise	Before countermeasure	After countermeasure
Common mode noise (inverter noise) (Common noise applied between the mounting board and the +V and 0-V lines, respectively.	Noise enters from the noise source through the frame (metal).	<ul> <li>(1) Ground the inverter motor (to 100 Ω or less)</li> <li>(2) Ground the noise source and the power supply (0-V side) through a capacitor (film capacitor, 0.22 μF, 630 V).</li> <li>(3) Insert an insulator (plastic, rubber, etc.) between the Sensor and the mounting plate (metal).</li> </ul>
Radiant noise (Ingress of high-fre- quency electromag- netic waves directly into Sensor, from power line, etc.	Noise propagates through the air from the noise source and directly enters the Sensor.	<ul> <li>Insert a shield (copper) plate between the Sensor and the noise source e.g., a switching power supply).</li> <li>Separate the noise source and the Sensor to a distance where noise does not affect operation.</li> </ul>
Power line noise (Ingress of electromag- netic induction from high-voltage wires and switching noise from the switching power supply	Noise enters from the power line.	Insert a capacitor (e.g., a film capacitor), noise filter (e.g. ferrite core or insulated transformer), or varistor in the power line.  Insert a capacitor, etc.  Sensor  Viscon O+V OV

#### Wiring

#### Cable

Unless otherwise indicated, the maximum length of cable extension is 100 m using wire that is  $0.3\ mm^2$  or greater.

Exceptions are indicated in *Safety Precautions* in individual product information.

#### **Cable Tensile Strength**

When wiring the cable, do not subject the cable to a tension greater than that indicated in the following table.

Cable diameter	Tensile strength
Less than 4 mm	30 N max.
4 mm or greater	50 N max.

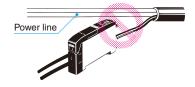
Note: Do not subject a shielded cable or coaxial cable to tension.

#### **Repeated Bending**

Normally, the Sensor cable should not be bent repeatedly. (For bending-resistant cable, see *Attachment to Moving Parts* on page **C-4**.)

#### Separation from High Voltage (Wiring Method)

Do not lay the cables for the Sensor together with high-voltage lines or power lines. Placing them in the same conduit or duct may cause damage or malfunction due to induction interference. As a general rule, wire the Sensor in a separate system, use an independent metal conduit, or use shielded cable.



#### Work Required for Unconnected Leads

Unused leads for self-diagnosis outputs or other special functions should be cut and wrapped with insulating tape to prevent contact with other terminals.

#### **Power Supply**

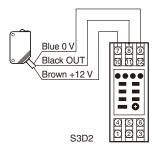
When using a commercially available switching regulator, ground the FG (frame ground) and G (ground) terminals.

If not grounded, switching noise in the power supply may cause malfunction.

#### Example of Connection with S3D2 Sensor Controller

#### **DC Three-wire NPN Output Sensors**

Reverse operation is possible using the signal input switch on the S3D2.



#### Mounting

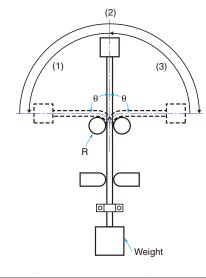
#### **Attachment to Moving Parts**

To mount the Photoelectric Sensor to a moving part, such as a robot hand, consider using a Sensors that uses a bending-resistant cable (robot cable).

Although the bending repetition tolerance of a standard cable is approximately 13,000 times, robot cable has an excellent bending tolerance of approximately 500,000 times.

## Cable Bending Destruction Test (Tough Wire Breaking Test)

With current flowing, bending is repeated to check the number of bends until the current stops.



Те	Specimen st	Standard cable VR (H) 3 x18/0.12	Robot cable: Strong, conductive electrical wire 2 x 0.15 mm <sup>2</sup> , shielded
S	Bending angle (θ)	Left/right 90° each	Left/right 45° each
dition	Bending repetitions		60 bends/minute
con	Weight	300g	200g
Description/conditions	Operation per bending	(1) through (3) in figure once	(1) through (3) in figure once
Descri	Bending radius of support points (R)	5 mm	2.5 mm
Re	sult	Approx. 13,000 times	Approx. 500,000 times

The testing conditions of the standard cable and robot cable are different.

Refer to the values in the above table to check bend-resistant performance under actual working conditions.

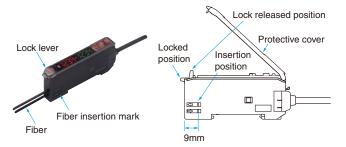


#### **Securing Fibers**

The E3X Fiber Unit uses a one-touch locking mechanism. Use the following methods to attach and remove Fiber Units.

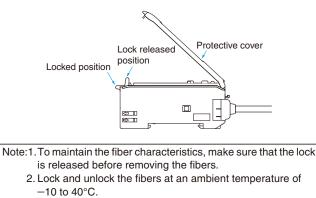
#### (1) Attaching Fibers

Open the protective cover, insert the fiber up to the insertion mark on the side of the Fiber Unit, and then lower the lock lever.



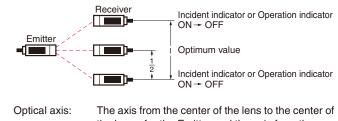
#### (2) Removing Fibers

Open the protective cover, lift up the lock lever, and pull out the fibers.



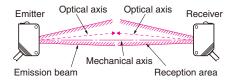
## Adjustments Optical Axis Adjustment

Move the Photoelectric Sensor both vertically and horizontally and set it in the center of the range in which the operation indicator is lit or not lit. For the E3S-C, the optical axis and the mechanical axis are the same, so the optical axis can be easily adjusted by aligning the mechanical axis.



the beam for the Emitter and the axis from the center of the lens to the center of the reception area for the Receiver.

Mechanical axis: The axis perpendicular to the center of the lens.



#### Operating Environment

#### Water Resistance

Do not use in water, in rain, or outside.

#### **Ambient Conditions**

Do not use this Sensor in the following locations. Otherwise, it may

- malfunction or fail.
- (1) Locations exposed to excessive dust and dirt (2) Locations exposed to direct sunlight
- (3) Locations with corrosive gas vapors
- (4) Locations where organic solvents may splash onto the Sensor
- (5) Locations subject to vibration or shock
- (6) Locations where there is a possibility of direct contact with water, oil, or chemicals
- (7) Locations with high humidity and where condensation may result

#### **Environmentally Resistive Sensors**

The E32-T11F/T12F/T14F/T81F-S/D12F/D82F and E3HQ can be used in locations (3) and (6) above.

#### **Optical Fiber Photoelectric Sensors in Explosive Gas Atmospheres**

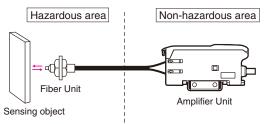
The Fiber Unit can be installed in the hazardous area, and the Amplifier Unit can be installed in a non-hazardous area.

#### <Reason>

For explosion or fire due to electrical equipment to occur, both the hazardous atmosphere and a source of ignition must be in the same location. Optical energy does not act as an ignition source, thus there is no danger of explosion or fire. The lens, case, and fiber covering are made of plastic, so this setup cannot be used if there is a possibility of contact with solvents that will corrode or degrade (e.g., cloud) the plastic.

#### <Ignition Source>

Electrical sparks or high-temperature parts that have sufficient energy to cause explosion in a hazardous atmosphere are called ignition sources.



#### Influence from External Electrical Fields

Do not bring a transceiver near the Photoelectric Sensor or its wiring, because this may cause incorrect operation.

#### Maintenance and Inspection

#### Points to Check When the Sensor Does Not Operate

- If the Sensor does not operate, check the following points.
- (1) Are the wiring and connections correct?
- (2) Are any of the mounting screws loose?
- (3) Are the optical axis and sensitivity adjusted correctly?
- (4) Do the sensing object and the workpiece speed satisfy the ratings and specifications?
- (5) Are any foreign objects, such as debris or dust, adhering to the Emitter lens or Receiver lens?
- (6) Is strong light, such as sunlight (e.g., reflected from a wall), shining on the Receiver?
- (7) Do not attempt to disassemble or repair the Sensor under any circumstances.
- (8) If you determine that the Sensor clearly has a failure, immediately turn OFF the power supply.

#### Lens and Case

The lens and case of the Photoelectric Sensor are primarily made of plastic. Dirt should be gently wiped off with a dry cloth. Do not use thinner or other organic solvents.

• The case of the E3ZM, E3ZM-C and E3S-C is metal. The lens, however, is plastic.

#### Accessories

#### Using a Reflector (E39-R3/R37/RS1/RS2/RS3) **During Application**

- (1) When using adhesive tape on the rear face, apply it after washing away oil and dust with detergent. The Reflector cannot be mounted if there is any oil or dirt remaining.
- (2) Do not press on the E39-RS1/RS2/RS3 with metal or a fingernail. This may weaken performance.
- (3) This Sensor cannot be used in locations where oil or chemicals may splash on the Sensor.

#### M8 and M12 Connectors

- · Be sure to connect or disconnect the connector after turning OFF the Sensor.
- Hold the connector cover to connect or disconnect the connector.
- · Secure the connector cover by hand. Do not use pliers, otherwise the connector may be damaged.
- If the connector is not connected securely, the connector may be disconnected by vibration or the proper degree of protection of the Sensor may not be maintained.

#### Others

#### Values Given in Typical Examples

The data and values given as typical examples are not ratings and performance and do not indicate specified performance. They are rather values from samples taken from production lots, and are provided for reference as guidelines. Typical examples include the minimum sensing object, engineering data, step (height) detection data, and selection list for specifications.

#### Cleaning

- Keep organic solvents away from the Sensor. Organic solvents will dissolve the surface.
- Use a soft, dry cloth to clean the Sensor.

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