Instruction manual

To prevent accidents arising from the misuse of this controller, please ensure the operator using it receives this manual.

SAFETY PRECAUTIONS

Be sure to read these precautions before using our products.

The safety precautions are classified into categories: "Warning" and "Caution".

A Warning : Procedures which may lead to dangerous conditions and cause death or serious injury, if not

carried out properly.

A Caution : Procedures which may lead to dangerous conditions and cause superficial to medium injury or physical damage or may degrade or damage the product, if not carried out properly.



• When using this controller on occasions which serious injury would be expected to occur or when damage is likely to expand or proliferate, make sure to take safety measures such as installing double safety structures.

• Do not use this controller in an environment with flammable gases, or it may cause explosion.



- Fasten the electric wire with the terminal screws securely. Imperfect connection may cause abnormal heating or fumes.
- Use this controller according to the rating and environmental conditions. Otherwise abnormal heating or fumes may occur.
- Do not touch the terminals while the power is supplied to the controller, as this may cause electric shock.
- Do not disassemble or modify the controller, as this may cause electric shock or fumes.

A Caution

- This instrument should be used according to the specifications described in this manual. If it is not used according to the specifications, it may malfunction or cause fire.
- Be sure to follow the warnings, cautions and notice. If not, it could cause serious injury or accidents.
- The contents of this instruction manual are subject to change without notice.
- This instrument is designed to be installed in a control panel. If not, measures must be taken to ensure that the operator cannot touch power terminals or other high voltage sections.
- Be sure to turn the power supplied to the instrument OFF before cleaning this instrument.
- Use a soft, dry cloth when cleaning the instrument. (If paint thinner is used, it might deform or tarnish the unit.)
- As the display section is vulnerable, do not strike or scratch it with a hard object.
- Any unauthorized transfer or copying of this document, in part or in whole, is prohibited.

• Tatsuno Matsushita Electric Works, Ltd. is not liable for any damages or secondary damages incurred as a result of using this product, including any indirect damages.

1. Model number

1.1 Explanation of model number

| $A K T 7 1 10 \\ \uparrow \uparrow \uparrow \uparrow \uparrow$ | ↑ |
|--|--|
| (1) (2) (3) (4) | (5) |
| (1) Supply voltage | 1: 100 to 240V AC, 2: 24V AC/DC |
| (2) Input type | 1: Multi-input (Thermocouple, RTD, DC current and DC voltage can be selected by key operation) |
| (3) Control output (OUT) | 1: Relay contact, 2: Non-contact voltage, 3: DC current |
| (4) Alarm output | 1: Alarm output (1 point) |
| | (The alarm action and Energized /Deenergized can be selected by key operation) |
| (5) Heater burnout alarm Available | 0: Not available, 1: Available (5A), 2: Available (10A), 3: |
| | (20A), 4: Available (50A) |
| | (Heater burnout alarm is not available for the DC current output) |

1.2 How to indicate the rated label

The rated label is put on the case.

When Heater burnout alarm is added, CT rated current is written in the bracket.



(1) Model number, supply voltage, input type, output type, etc. are entered.

(2) Lot number is entered.

2. Name and functions of the sections

(1) EVT indicator

A red LED lights up when Event output [Alarm, Loop break alarm or Heater burnout alarm (Option)] is ON.

(2) OUT indicator

When OUT output is ON, a green LED lights up.

For DC current output type, this blinks corresponding to the output manipulated variable.

(3) AT indicator

A yellow LED blinks while PID auto-tuning is being performed. (4) PV display

- Indicates the input value (PV) with a Red LED.
- (5) SV display

Indicates the setting value (SV) with a Green LED.

- (6) Increase key Increases the numeric value.
- (7) Decrease key Decreases the numeric value.
- (8) Mode key

Selects the setting mode or registers the setting value.

(By pressing the Mode key, the setting value can be registered) (9) Sub mode key

Brings up Auxiliary function setting mode 2 with the Mode key.



(Fig. 2-1)

Notice

When setting the specifications and functions of this controller, connect the terminals 1 and 2 for power source first, then set them referring to "5. Setup" before performing "3. Mounting to control panel" and "4. Wiring connection".

3. Mounting to control panel

3.1 Site selection

This instrument is intended to be used under the following environmental conditions (IEC61010-1): Overvoltage category \mathbb{I} , Pollution degree 2

Mount the controller in a place with:

- A minimum of dust, and an absence of corrosive gases
- No flammable, explosive gasses
- Few mechanical vibrations or shocks
- No exposure to direct sunlight, an ambient temperature of 0 to 50°C (32 to 122°F) that does not change rapidly
- An ambient non-condensing humidity of 35 to 85%RH
- No large capacity electromagnetic switches or cables through which large current is flowing
- No water, oil or chemicals or where the vapors of these substances can come into direct

contact with the controller

3.2 External dimension



3.4 Mounting to DIN rail

Caution

Mount the DIN rail horizontally.

When DIN rail is mounted vertically, be sure to use commercially available fastening plates at the end of KT7 series. Mount the KT7 series to the DIN rail so that the KT7 series cannot move.

However, if the DIN rail is mounted horizontally in a position susceptible to vibration or shock, the fastening plates must be used as well.

Recommended fastening plate

| Matsushita electric works, LTD. | Fastening plate | ATA4806 |
|---------------------------------|-----------------|---------|

- (1) Hook (1) of KT7 series on the upper side of the DIN rail. (Fig. 3.4-1)
- (2) Making the (1) part of the KT7 series as a support, fit the lower part of the KT7 series to the DIN rail. KT7 series will be completely fixed to DIN rail with a "Click" sound. (Fig. 3.4-1)



(Fig. 3.4-1)

4. Wiring connection

🗥 Warning

Turn the power supplied to the instrument OFF before wiring or checking it. Working or touching the terminal with the power switched ON may result in Electric Shock causing severe injury or death.

A Caution

- Do not leave wire chips in the KT7 series when wiring, because they could cause fire, malfunction and trouble.
- Insert the connecting cable into the designated connector securely. Otherwise malfunction due to imperfect contact may occur.
- Connect the AC power wire to the designated terminal as is written in this instruction manual, otherwise it may burn and damage the KT7 series.
- Tighten the terminal screw with the specified torque. If not, it may damage the terminal screw and deform the case.
- Use thermocouple and compensating lead wire that fit sensor input specification of this unit.
- Use the 3-wire RTD that corresponds to the sensor input specification of this unit.
- When using DC voltage and current input types, do not confuse the polarity when wiring.
- When using a 24V AC/DC for the power source, do not confuse the polarity when it is DC.
- Keep input wires (Thermocouple, RTD, etc) away from power source and load wires to avoid external interference.
- To prevent the unit from harmful effects of the unexpected level noise, it is recommended that a surge absorber be installed between the electromagnetic switch coils.
- This unit does not have built-in power switch, circuit breaker or fuse. Therfore, it is necessary to install them in the circuit near the external unit.
- (Recommended fuse: Time-lag fuse, rated voltage 250V AC rated current 2A)

Note

Tighten the terminal screw properly referring to the table below.

| Terminal screw | Terminal No. | Torque |
|----------------|--------------|----------------|
| M2.6 | 1 to 4 | Max. 0.5N 🛍 m |
| M2.0 | 5 to 9 | Max. 0.25N 🛍 m |



5. Setup

Wire the power terminals only. After the power is turned on, the sensor input characters and temperature unit are indicated on the PV display and the input range high limit value is indicated on the SV display for approx. 3 seconds (Table 5-1).

(If any other value is set in the scaling high limit value, it is indicated on the SV display.) During this time all outputs and the LED indicators are in OFF status.

Control will then start and the input value will be indicated on the PV display and setting value will be indicated on the SV display.

(Table 5-1)

| Input type | Input range | | Resolution |
|--------------|-------------------|-------------------|------------|
| | -200 to 1370 | -320 to 2500 | 1℃ |
| ĸ | Ĵ | °F | (°F) |
| | –199.9 to | –199.9 to 750.0°F | 0.1℃ |
| | 400.0℃ | | (°F) |
| | -200 to1000 | –320 to1800 °F | 1℃ |
| 0 | °C | | (°F) |
| R | 0 to | 0 to | 1℃ |
| | 1760 °C | 3200 °F | (°F) |
| S | 0 to | 0 to | 1°C |
| 0 | 1760 °C | 3200 °F | (°F) |
| В | 0 to | 0 to | 1℃ |
| d | 1820 °C | 3300 °F | (°F) |
| F | -200 to 800 | -320 to 1500 | 1℃ |
| | Ĵ | °F | (°F) |
| т | –199.9 to | –199.9 to 750.0°F | 0.1℃ (°F) |
| | 400.0℃ | | |
| N | -200 to 1300 | -320 to 2300 | 1℃ |
| IN | °C | °F | (°F) |
| | 0 to | 0 to | 1°C |
| | 1390 °C | 2500 °F | (°F) |
| C(W//Re5-26) | 0 to | 0 to | 1℃ |
| 0(00/100-20) | 2315 °C | 4200 °F | (°F) |
| Pt100 | –199.9 to 850.0 ℃ | −199.9 to 999.9°F | 0.1℃ (°F) |

*1: Input range and decimal point place can be changed.

| | -200 to 850 | -300 to 1500 | 1°C |
|-----------------|-------------------|-------------------|-----------|
| | °C | °F | (°F) |
| | –199.9 to 500.0 ℃ | −199.9 to 900.0°F | 0.1℃ (°F) |
| JPt100 | -200 to 500 | -300 to 900 | 1°C |
| | °C | °F | (°F) |
| 4 to 20 mA DC | | -1999 to 9999 | 1 |
| 4 10 2011A DC | *1,*2 | | |
| 0 to 20 mA DC | | -1999 to 9999 | 1 |
| 0 10 20117 DO | *1,*2 | | |
| 0 to 1V DC | | -1999 to 9999 | 1 |
| 0101000 | *1 | | |
| 0 to 5V DC | | -1999 to 9999 | 1 |
| 01000000 | *1 | | |
| 1 to 5V DC | | -1999 to 9999 | 1 |
| 1.001.00 | *1 | | |
| 0 to 10V DC | | -1999 to 9999 | 1 |
| 0.0 100 00 | *1 | | |

5.1 Setup flow chart



| Output status selection when input burnout $[\mathcal{E} \cap \mathcal{U}^{\Gamma}]$ AT bias setting $[\mathcal{R}^{\Gamma} - b]$ | וg |
|--|------|
| MODE | MODE |
| ✓ | _ |
| $\mathbf{V}_{\mathbf{M}} = \mathbf{W}_{\mathbf{M}} = $ | |
| Image: Model (Approx. 3s): Press the Model for 3 seconds while the key is being pressed. Image: Model (Approx. 3s): Press the Model for 3 seconds while the tem Image: Model (Approx. 3s): Press the Model for 3 seconds while the tem Image: Model (Approx. 3s): Press the Model for 3 seconds while the tem Image: Model (Approx. 3s): Press the Model for 3 seconds while the for 3 seconds while the Image: Model (Approx. 3s): Press the Model (Approx. 3s): Press the for 3 seconds while the Image: Model (Approx. 3s): Press the Model (Approx. 3s): Press the (Approx. 3s): Press the Image: Model (Approx. 3s): Press the Model (Approx. 3s): Press the (Approx. 3s): Press the Image: Model (Approx. 3s): Press the (Approx. 3s): Press the (Approx. 3s): Press the (Approx. 3s): Press the Image: Model (Approx. 3s): Press the (Approx. 3s): Press the (Approx. 3s): Press the (Approx. 3s): Press the Image: Model (Approx. 3s): Press the (Approx. 3s): Press the (Approx. 3s): Press the Image: Model (Approx. 3s): Press the (Approx. 3s): Press the (Approx. 3s): Pr | |
| There are some setting characters which are not indicated depending on the specification. | |

5.2 Main setting mode

| Character | Name, Description, Setting range | Default value |
|-----------|--|---------------|
| 5 | SV | 0°C |
| | Sets the value for controlled object. | |
| | • Setting range: Scaling low limit value to scaling high limit value | |
| | (For DC voltage and current inputs, the placement of the | |
| | decimal point follows the selection) | |

5.3 Sub setting mode

| Character | Name, Description, Setting range | Default value |
|------------|---|---------------|
| 85 | AT setting | |
| | • Performs PID auto-tuning. However when PID auto-tuning has | |
| | not finished after 4 hours, PID auto-tuning is cancelled | |
| | automatically. | |
| | • PID auto-tuning cancellation: | |
| - | PID auto-tuning performance: Ri | |
| ۶ | OUT proportional band setting | 2.5% |
| | • Sets the proportional band. • The control action becomes ON/OEE action when set to 0.0 | |
| | • Setting range: 0.0 to 110.0% | |
| ; | Integral time setting | 200 seconds |
| | Sets the integral time. | 200 0000100 |
| | Setting the value to 0 disables the function. | |
| | This setting item is not indicated for ON/OFF action. | |
| | Setting range: 0 to 1000 seconds | |
| 6 | Derivative time setting | 50 seconds |
| | Sets the derivative time. | |
| | • Setting the value to 0 disables the function. | |
| | • This setting item is not indicated for ON/OFF action. | |
| 0 | Anti-reset windun setting | 50% |
| | Sets anti-reset windup. | 50 /0 |
| | Available only for PID action. | |
| | Setting the value to 0 disables the function. | |
| | Setting range: 0 to 100% | |
| C | OUT proportional cycle setting | 30 seconds |
| | • Sets the proportional cycle value for the control output (OUT). | or 3 seconds |
| | Not available for ON/OFF action or DC current output | |
| | Setting range: 1 to 120 seconds | |
| - 485 | Manual reset setting | 0.0 |
| | Sets the reset value manually. | |
| | Available only for P and PD action. | |
| | • \pm Proportional band converted value (For DC voltage and | |
| | current inputs, the placement of the decimal point follows the | |
| <i>.</i> | Selection) | ^ |
| <i>~ '</i> | Alarm setting | 00 |
| | • Sets the action point for the diarm output. | |
| | (evoluting Process high and Process low alarms) | |
| | When Loop break alarm and Heater burnout alarm are applied | |
| | together the output is common | |
| | Not available if No alarm action is selected in the Alarm action | |
| | selection. | |
| | • See (Table 5.3-1), (For DC voltage and current inputs, the | |
| | placement of the decimal point follows the selection) | |

| Н | Heater burnout alarm setting | 0 0A |
|------|--|-----------|
| | Sets the heater current value for Heater burnout alarm. | |
| | Setting the value to 0.0 disables the function. | |
| | Self-holding is not available for the alarm output. | |
| | When alarm and Loop break alarm are applied together. | |
| | the output is common. | |
| | Available only when Heater burnout alarm is added. | |
| | • Rating 5A : 0.0 to 5.0A Rating 10A: 0.0 to 10.0A | |
| | Rating 20A: 0.0 to20.0A Rating 50A: 0.0 to 50.0A | |
| LP_F | Loop break alarm action time setting | 0 minutes |
| | Sets the action time to assess the Loop break alarm. | |
| | Setting the value to 0 disables the function. | |
| | • When alarm and Heater burnout alarm are applied together, | |
| | the output is common. | |
| | Setting range: 0 to 200 minutes | |
| LP_H | Loop break alarm action span setting | 0°C |
| | Sets the action span to assess the Loop break alarm. | |
| | Setting the value to 0 disables the function. | |
| | • When alarm and Heater burnout alarm are applied together, | |
| | the output is common. | |
| | Setting range | |
| | Thermocouple and RTD inputs: 0 to 150° (F) or | |
| | 0.0 to 150.0℃ (°F) | |
| | DC voltage and current inputs: 0 to 1500 (The placement of the | |
| | decimal point follows the selection) | |

(Table 5.3-1)

| Alarm action type | Setting range | |
|-------------------------------|---|----------------|
| High limit alarm | –(Scaling span) to scaling span | Negative low |
| Low limit alarm | –(Scaling span) to scaling span | limit value is |
| High/Low limits alarm | 0 to scaling span | –199.9 or |
| High/Low limit range alarm | 0 to scaling span | –1999. |
| Process high alarm | Scaling low limit value to scaling high limit value | |
| Process low alarm | Scaling low limit value to scaling high limit value | Positive high |
| High limit alarm with standby | –(Scaling span) to scaling span | limit value is |
| Low limit alarm with standby | –(Scaling span) to scaling span | 999.9 or 9999. |
| High/Low limits with standby | 0 to scaling span | |

5.4 Auxiliary function setting mode 1

| Character | Name, Description, Setting range | Default value |
|-----------|--|---------------|
| Lock | Setting value lock selection | Unlock |
| | • Locks the setting value to prevent setting errors. | |
| | When Lock 1 or Lock 2 is designated, PID auto-tuning cannot be carried out. | |
| | ・ (Unlock): All setting values can be changed. L ロ こ / (Lock 1): None of setting values can be changed. L ロ こ ご (Lock 2): Only main setting mode can be changed. | |
| | $L \Box \subset \exists$ (Lock 3): All setting values can be changed except Controller/Converter | |
| | function selection. However they return to their | former value |
| | after power is turned off because they are not | saved in the |
| | non-volatile memory. | |

| 60 | Sensor correction setting | 0.0°C |
|----|--|-------|
| | Sets the sensor correction value for the sensor. | |
| | Thermocouple and RTD inputs: –100.0 to 100.0℃ (°F) | |
| | DC voltage and current inputs: -1000 to 1000 (The placement of | |
| | the decimal point follows the selection) | |

5.5 Auxiliary function setting mode 2

| Character | Name, Description, Setting range | Default value |
|-----------|---|---------------------|
| 5En5 | Input type selection | K |
| | • The input type can be selected from thermocouple (22 types), | (–200 to 1370℃) |
| | RTD (8 types), DC current (2 types) and DC voltage(4 types), | |
| | and the unit °C/F can be selected as well. | |
| | K $-200 \text{ to } 1370^{\circ}\text{C}$: E ζ K $-320 \text{ to } 2500$ | °F: E E |
| | –199.9 to 400.0℃: 上199.9 to 7 | 50.0°F: |
| | J = -200 to 1000 °C: $i = J = -320 to 1800$ | F: U F |
| | R = 0 to 1/60 C: $r = 1 R = 0 to 3200$ | |
| | | |
| | $\begin{bmatrix} B & 0 & 10 & 10 & 20 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 &$ | г. U / ъ Е Е |
| | $T = -199.9 \text{ to } 400.0^{\circ}\text{C} \cdot \int \int T$ | -199.9 to |
| | N $-200 \text{ to } 1300 \degree \text{C}; \square \square$ | 100.0 10 |
| | PL-II 0 to 1390 °C: PL 2C N −320 to 2300 | °F: 🗗 🖌 🗲 |
| | C (W/Re5-26)0 to 2315 °C: | 00 °F: <i>PL2F</i> |
| | Pt100 −199.9 to 850.0°C: Pr . C (W/Re5-26) 0 | to 4200 °F: 🗲 |
| | JPt100 –199.9 to 500.0℃:_ <i>_」に下に、</i> F | |
| | Pt100 –200 to 850 °C: P_{i}^{r} L Pt100 –199.9 to 9 | 999.9°F: <i>PIF</i> |
| | JPt100 –200 to 500 ℃: JPt1C JPt100 –199.9 to 9 | 900.0°F: 2171.7 |
| | Pt100 -300 to 15 | |
| | JPt100 -300 to 9 | 100 F: UFIF |
| | $\begin{array}{cccccccccccccccccccccccccccccccccccc$ | |
| | $0 \text{ to } 20\text{ mA}$ = 1999 to 9999. \square \square | |
| | 0 to 5V -1999 to 9999 $\Box 5H$ | |
| | 1 to 5V -1999 to 9999: 758 | |
| | 0 to 10V –1999 to 9999: 🖸 🖉 🗄 | |
| 55LH | Scaling high limit setting | 1370℃ |
| | Sets the scaling high limit value. | |
| | • Setting range: Scaling low limit value to input range high limit | |
| | Value | |
| | (For DC voltage and current inputs, the placement of the decimal point follows the selection) | |
| 5511 | Scaling low limit setting | 200°C |
| " " " " | Sets the scaling low limit value. | -2000 |
| | Input range low limit value to scaling high limit value | |
| | (For DC voltage and current inputs, the placement of the | |
| | decimal point follows the selection.) | |
| 8P | Decimal point place selection | No decimal |
| | Selects decimal point place. | point |
| | Available only for DC input. No desimal point. | |
| | 2 digits after decimal point, 3 digits after decimal point | |
| E: : [| PV filter time constant setting | 0.0 seconds |
| | Sets PV filter time constant. | 0.0 3000103 |
| | (If the setting value is too large, it affects control result due to | |
| | the delay of response) | |
| | Setting range: 0.0 to 10.0 seconds | |
| oLH | OUT high limit setting | 100% |
| | Sets the control output high limit value. | |
| | Not available for ON/OFF action. | |
| | Setting range: OUT low limit value to 105% | |
| | (Setting greater than 100% is effective to DC current output type) | |

| all | OUT low limit setting | 0% |
|--------|--|------------------|
| | Sets the control output low limit value. | 0,0 |
| | Not available for ON/OFF action | |
| | • Setting range: -5% to OUT high limit value | |
| | (Setting less than 0% is effective to DC current output type) | |
| 895 | OUT ON/OFF action hysteresis setting | 1.0°C |
| | • Sets the ON/OFE action hysteresis for the control output | 1.0 0 |
| | • Available only when the control action is ON/OFE action (P=0) | |
| | Setting range | |
| | Thermocouple and RTD inputs: 0.1 to 100 $0^{\circ}C^{\circ}F$ | |
| | DC voltage and current inputs 1 to 1000 (The placement of the | |
| | decimal point follows the selection) | |
| 81. IE | Alarm action selection | No alarm action |
| | Selects an alarm action type. | |
| | No alarm action : | |
| | High limit alarm action : H | |
| | Low limit alarm action : L | |
| | High/Low limits alarm action H_{L} | |
| | High/Low limit range alarm action | |
| | Process high alarm action | |
| | Process low alarm action $-B^{-}$ | |
| | High limit alarm action with standby $H = \bar{\mu}$ | |
| | Low limit alarm action with standby $L = \frac{1}{4}$ | |
| | High/Low limits alarm action with standby: H_{L} | |
| 8 ILA | Alarm action Energized/Deenergized selection | Energized |
| | Selects the alarm action Energized/Deenergized. | 5 |
| | • Not available if No alarm action is selected in the Alarm action | |
| | selection. | |
| | •Energized: つロー Deenergized: ことと | |
| RHLd | Alarm HOLD function selection | Alarm HOLD |
| | Selects whether alarm HOLD function is [Used] or [Not used]. | [Not used] |
| | If alarm HOLD function is set to [Used], once the alarm | |
| | functions, alarm output remains until the power is turned off. | |
| | • Not available if No alarm action is selected in the Alarm action | |
| | selection | |
| | • Alarm HOLD [Not used]: | |
| | Alarm HOLD [Used] : Hold | |
| H INS | Alarm hysteresis setting | 1.0℃ |
| | • Sets the alarm hysteresis. | |
| | | |
| | | |
| | Thermosouple and PTD inpute: 0.1 to 100.0°C($^{\circ}$ E) | |
| | DC voltage and current inputs: 1 to 1000 (The placement of the | |
| | decimal point follows the selection) | |
| 8 124 | Alarm action delayed timer setting | 0 seconds |
| | Sets the alarm action delayed time | 0 3000103 |
| | When the setting time has passed after the input enters alarm | |
| | output range alarm output activates | |
| | Not available if No alarm action is selected in the Alarm action | |
| | selection | |
| | Setting range: 0 to 9999 seconds | |
| conf | Direct/Reverse selection | Reverse |
| | Selects Reverse (heating) or Direct (cooling) control action. | (Heating) action |
| | • Reverse (Heating) action : HERF | |
| | Direct (Cooling) action | |

| ЯГ <u></u> ь | AT bias setting Set bias value during PID auto-tuning. Not available if DC voltage or current input is selected in the Input type selection and when action is not PID, either. Setting range: 0 to 50°C (0 to 100°F) or 0.0 to 50.0°C (0.0 to 100.0°F) | 20°C |
|--------------|--|------------------------|
| FUnc | Controller/ Converter function selection Selects controller or converter function. This setting item is indicated only when the control output is DC current output type. Controller function : こっぱっ Converter function : こっぱっ | Controller function |
| ΕουΓ | Output status selection when input burnout Selects whether the OUT output is turned OFF or not when DC input is overscale or underscale. Available only for DC current output type with DC input. □FF (Output OFF) □□ (Output ON) | Output OFF |

Sensor correction function

This corrects the input value from the sensor. When a sensor cannot be set at a location where control is desired, the sensor measuring temperature may deviate from the temperature in the controlled location. When controlling with plural controllers, the accuracy of sensors affects the control. Therefore, sometimes the measured temperature (input value) does not concur with the same setting value. In such a case, the control can be set at the desired temperature by adjusting the input value of sensors.

Loop break alarm

The alarm will be activated when the process variable (PV) does not **rise** to the span within the time it takes to assess the Loop break alarm after the manipulated variable has reached 100% or the output high limit value.

The alarm will also be activated when the process variable (PV) does not **fall** to the span within the time it takes to assess the Loop break alarm after the manipulated variable has reached 0% or the output low limit value.

When the control action is Direct (Cooling), read "fall" for "rise" and vice versa.

Energized/Deenergized function

When [alarm action energized] is selected, the alarm output (between terminals 8-9) is conducted (ON) while the alarm output indicator is lit.

The alarm output is not conducted (OFF) while the alarm output indicator is not lit.

When [alarm action deenergized] is selected, the alarm output (between terminals 8-9) is not conducted (OFF) while the alarm output indicator is lit.

The alarm output is conducted (ON) while the alarm output indicator is not lit.



High limit alarm (When Energized is set)



5.6 Output manipulated variable indication

Name and Description

Output manipulated variable indication

• In the PV/SV display mode, press the MODE key for approx. 3 seconds.

Keep pressing the MODE key until the output manipulated variable shows up, though the main setting mode appears temporarily during the process.

(The SV display indicates output manipulated variable and the 1st decimal point from the right blinks in a 0.5 second cycle)

If the MODE key is pressed again, the mode reverts to the PV/SV display.

6. Converter function

L Caution

• When using this controller as a converter, take 1 second into consideration since input/output response time is approx. 1 second.

• When switching from converter function to controller function, the control parameter and values set by converter function are held even if the function is switched to controller function.

So, correct the control parameter and values which are set by converter function to the value necessary for the controller function after switching to the controller function.

The converter function of this instrument converts each input (thermocouple, RTD, DC voltage and DC current inputs) value to "4 to 20mA DC" and outputs it using the control parameter of the controller.

When this instrument is used as a converter, follow the process (1) to (7) described below.

After the process (1) to (7) is finished, this instrument can be used as a converter.

(1) Wire and connect this controller (Power, Input and Output).

(2) Turn the power of this controller ON.

(3) Bring up "Auxiliary function setting mode 2" by pressing the _____ and _____ key (for approx. 3s).

(4) Select the sensor type from "Input type selection $(\neg \Xi \neg \neg)$ ".

(5) Set the high limit of the value that is going to be converted during "Scaling high limit setting $(\neg \vdash L H)$ ".

(6) Set the low limit of the value that is going to be converted during "Scaling low limit setting $(\neg \Gamma \downarrow H)$ ".

(7) Select converter ($c \neg d \Gamma$) from "Control/ Converter function selection ($F \sqcup \neg c$)".

• To activate the alarm action by Converter function, set the alarm action to Process alarm action.

If converter function is selected from "Controller/Converter function selection" in Auxiliary function setting mode 2, the parameter below is automatically set. (Table 6-1)

However, this is applied only to the DC current output type.

| (Table 6-1 |) |
|------------|---|
|------------|---|

| Setting item | Setting value | Setting item | Setting value |
|----------------------|-------------------|---------------------------------|---------------|
| SV | Scaling low limit | Alarm setting | 0 |
| Proportional band | 100.0% | Loop break alarm action time | 0 seconds |
| Integral time | 0 seconds | Loop break alarm action span | 0 |
| Derivative time | 0 seconds | Direct/Reverse action selection | Direct action |
| Manual reset setting | 0.0 | | |

7. Running

After mounting and wiring in the control panel (DIN rail) are finished, running is started in the following manner.

(1) Turn the power supply to the KT7 Series ON.

For approx. 3s after power is turned on, the character of the sensor type and temperature unit are indicated on the PV display, and the rated maximum value is indicated on the SV display. See [Table 5-1].

(If any other value is set in the scaling high limit value setting, SV display indicates it) During this time, all outputs and LED indicators are in OFF status.

After that, PV display indicates actual temperature and SV display indicates the main setting value. (2) Input each setting value.

Input each setting value, referring to "5. Setup".

(3) Turn the load circuit power ON.

Starts the control action so as to keep temperature of the controlled object at the main setting value.

8. Action explanation 8.1 OUT action

| | Heating (Reverse) action | Cooling (Direct) action | | |
|-------------------------------|--|---|--|--|
| Control action | ON Proportional band OFF | OFF | | |
| Relay contact output | Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system <t< td=""><td>3 3 3 5 5 5 Cycle action is performed according to deviation</td></t<> | 3 3 3 5 5 5 Cycle action is performed according to deviation | | |
| Non-contact voltage output | $\begin{array}{c c} + 3 & + 3 & + 3 & + 3 & \\ 12V DC & 12/0V DC & 0V DC \\ - 4 & - 4 & - 4 & - 4 & \\ Cycle action is performed according to deviation \\ \end{array}$ | $\begin{array}{c c} + & 3 \\ & 0 \\ - & 4 \\ \hline \end{array} \begin{array}{c} + & 3 \\ 0 \\ - & 4 \\ \hline \end{array} \begin{array}{c} + & 3 \\ 0 \\ - & 4 \\ \hline \end{array} \begin{array}{c} + & 3 \\ 1 \\ - & 4 \\ \hline \end{array} \begin{array}{c} - & 4 \\ - & 4 \\ \hline \end{array} \begin{array}{c} + & 3 \\ 1 \\ - & 4 \\ \hline \end{array} \begin{array}{c} - & 4 \\ - & 4 \\ \hline \end{array} \begin{array}{c} - & 4 \\ - & 4 \\ \hline \end{array} \begin{array}{c} - & 4 \\ - & 4 \\ \hline \end{array} \begin{array}{c} - & 4 \\ - & 4 \\ \hline \end{array} \begin{array}{c} - & 4 \\ - & 4 \\ \hline \end{array} $ | | |
| DC current output | $\begin{array}{c c} +3 & +3 & +3 & +3 \\ 20mA DC & 20 to 4mA DC & 4mA DC \\ -4 & -4 & -4 & -4 \\ \end{array}$ Changes continuously according to deviation | + 3 + 3 + 3 + 3 20mA DC - 4 to 20mA DC 20mA DC - 4 - 4 - 4 - 4 - 4 - 4 - 4 - 4 - 4 - 4 | | |
| Indication (OUT) Green | Lit Unlit | Unlit Lit | | |

part : Acts ON or OFF.

8.2 OUT ON/OFF action

| | Heating (reverse) action | | | Cooling (direct) action | | |
|-------------------------------|--------------------------|------------|-------------------|-------------------------|------------|--------------------|
| Control action | ON | Hysteresis | Setting | 2 | Hysteresis | ON OFF |
| Relay contact output | 3 | | 3 | 3 ا ها | | 3 |
| Non-contact voltage output | + 3 12V DC - 4 | | +3 0V DC -4 | + 3 0V DC - 4 | | +3 12V DC -4 |
| DC current output | + ③ 20mA DC - ④ | | + 3 | + 3 4mA DC - 4 | | +3 |
| Indication (OUT) Green | Lit | | Unlit | Unlit | | Lit |

8.3 EVT (Alarm) action



: Event (EVT) output terminals between 8 and 9 is ON.

Event (EVT) output terminals between 8 and 9 is ON or OFF.

- : Event (EVT) output terminals between 8 and 9 is OFF.
- : Standby functions in this section.

Event (EVT) output indicator lights up when output terminals between 8 and 9 is ON, and goes out when between them is OFF.

8.4 EVT (Heater burnout alarm) action



: Event (EVT) output terminals between 8 and 9 is ON

: Event (EVT) output terminals between 8 and 9 is OFF

Event (EVT) output indicator lights up when output terminals between 8 and 9 is ON and goes out when between them is OFF.

9. PID auto-tuning of this controller

In order to set each P, I, D values and ARW automatically, this system gives a fluctuation to the controlled object to get an optimal value.

One of 3 types of fluctuation below is automatically selected.

(1) When the difference between the setting value and processing temperature is large as the temperature rises.

When AT bias is set to $20^{\circ}C(^{\circ}F)$, a fluctuation is applied at the temperature $20^{\circ}C(^{\circ}F)$ lower than the setting value.



(2) When the control is stable

Fluctuation is applied at the setting value.



(3) When the difference between the setting value and processing temperature is large as the temperature falls

When AT bias is set to $20^{\circ}C(F)$, fluctuation is applied at the temperature $20^{\circ}C(F)$ higher than the setting value.



- (1): Calculating PID constacnt
- (2): PID constant calculated
- (3): Controlled by PID constant set by auto-tuning
- (4): AT bias value

▲ AT: Auto-tuning starting point

10. Specifications

| 10.1 Standa | rd specificatio | n | | | |
|-----------------|-----------------|--|------------------------------|---|------|
| Model n | name | : Temperature controller | | | |
| Mounting method | | : DIN rail mounting method | | | |
| Setting method | | : Input system using membrane sl | neet key | | |
| Display | | | | | |
| | PV display | : Red LED 4 digits, character size | 7.4 x 4mm (H | H x W) | |
| | | SV display | : Green LEI | D 4 digits, character size 7.4 x 4 | 4mm |
| (H x W) | | | | | |
| Input | | | | | |
| | Thermocouple | : K, J, R, S, B, E, T, N, PL-II, C (W However, for thermocouple B, ex | //Re5-26) «ternal resista | External resistance: 100Ω or lance, 40Ω or less | ess |
| | RTD | : Pt100, JPt100, 3-wire system | | | |
| | | A | Allowable inpu | ut lead wire resistance (10Ω or | less |

per wire)

DC current

: 0 to 20mA DC, 4 to 20mA DC, input impedance 50Ω [Connect 50^Ω shunt resistor (AKT4811, sold separately) between input terminals 5 and 6]

Allowable input current: 50mA or less

DC voltage

| | 0 to 1V DC | | 0 to 5V DC, 1 to 5V DC 0 to 10V DC | | |
|------------------------------------|------------|---------|---------------------------------------|--------|------------|
| Input impedance | 1M | Ω | or | 100kΩ | or greater |
| | great | er | | | |
| Allowable input voltage | 5V or | less | | 15V or | less |
| Allowable signal source resistance | 2kΩ | or less | | 100Ω | or less |
| · · · · · · · · · · | | | | | |

1

Accuracy (Setting and Indication)

Thermocouple : Within $\pm 0.2\%$ of input span ± 1 digit, or $\pm 2^{\circ}C$ (4°F) whichever is greater R, S input 0 to 200°C (0 to 400°F): Within $\pm 6^{\circ}$ C (12°F)

B input 0 to 300° (0 to 600° F): Accuracy is not guaranteed.

- K, J, E, N input, less than 0° (32°F): Within $\pm 0.4\%$ of input span ± 1 digit
- RTD : Within $\pm 0.1\%$ of input span ± 1 digit, or within $\pm 1^{\circ}C$ (2°F) whichever

is greater

- : Within \pm 0.2% of input span \pm 1 digit DC voltage
- DC current : Within $\pm 0.2\%$ of input span ± 1 digit

Input sampling period : 0.25 seconds

Control

Control action

- PID action (with auto-tuning function)
- PI action: When derivative time is set to 0
- PD action (with manual reset function): When integral time is set to 0
- P action (with manual reset function): When derivative and integral time are set to 0
- ON/OFF action: When proportional band is set to 0
 - OUT proportional band : 0.0 to 110.0% (ON/OFF action when set

to 0.0)

| Integral time | : 0 to 1000 seconds (Off when set to 0) |
|------------------------|--|
| Derivative time | : 0 to 300 seconds (Off when set to 0) |
| OUT proportional cycle | e: 1 to 120 seconds |
| ARW | : 0 to 100% |
| Manual reset | : \pm Proportional band converted value |
| Output limit | : 0 to 100% (DC current output type: –5 to 105%) |
| | (Not available for ON/OFF action) |
| Hysteresis | : Thermocouple and RTD inputs: 0.1 to 100.0°C (°F) |
| | DC voltage and current inputs: 1 to 1000 |
| | (The placement of the decimal point follows the selection) |
| Control output (OUT) | |

• Relay contact: 1a, Control capacity 3A

250V AC (Resistive load) 250V AC (Inductive load COS ø =0.4) 1A

Electrical life, 100,000 times

- Non-contact voltage (for SSR drive): 12^m, VDC Max. 40mA (Short circuit protected)
- DC current: 4 to 20mA DC, Load resistance: Max. 550Ω

Output accuracy: Within $\pm 0.3\%$ of output span Resolution : 12000

EVT output

 Alarm output [Common output with Loop break alarm and Heater burnout alarm (option)] The alarm action point is set by ± deviation to the main setting (excluding Process alarm) and when input exceeds the range in ± deviation setting (excluding Process alarm) to the main setting, alarm (EVT) turns ON or OFF (High/Low limit range alarm). When Deenergized is selected in the Energized/Deenergized selection, alarm (EVT) activates conversely. Setting accuracy : The same as indication accuracy Action : ON/OFF action Hysteresis : Thermocouple and RTD inputs: 0.1 to 100.0°C(°F) DC voltage and current inputs: 1 to 1000 (The placement of the

decimal

point follows the selection)

Output : Open collector, Control capacity 24V DC 0.1A (Max.)

Alarm output action : One alarm action is selectable from below by front key operation. High limit, Low limit, High/Low limits, High/Low limit range, Process high, Process low, High limit with standby, Low limit with standby, High/Low limits with standby and No alarm action

Energized/Deenergized: Alarm (EVT) output Energized/Deenergized can be selected.

| | Energized | Deenergized |
|---------------|-----------|-------------|
| Red (EVT) LED | Lights | Lights |
| EVT output | ON | OFF |

Alarm HOLD function selection: Once the alarm is activated, alarm output is held until the power is turned off.

• Loop break alarm output (Common output with Alarm and Heater burnout alarm [Option]) Detects heater burnout, sensor burnout, and abnormality at operation end.

Setting range: Loop break alarm action time setting: 0 to 200 minutes

Loop break alarm action span setting

Thermocouple and RTD inputs: 0 to 150°℃(°F) or 0.0 to 150.0°C(°F)

DC voltage and current inputs : 0 to 1500

(The placement of the decimal point follows the selection)

Output: Open collector, Control capacity, 24V DC 0.1A (Max.)

Converter function: See "6. Converter function"

Insulation • Dielectric strength: Circuit insulation configuration



Insulated resistance: $10M\Omega$ or greater at 500V DC Dielectric strength: 1.5kV AC for 1 minute between input

terminal and power terminal

 1.5kV AC for 1 minute between output terminal and power terminal

 Power consumption
 : Approx. 6VA

 Ambient temperature:
 0 to 50°C

 Ambient humidity
 : 35 to 85%RH (no condensation)

 Weight
 : Approx.120g

 External dimension
 : 22.5 x 75 x 100mm (W x H x D)

Material : Flame resistant resin (Case)

: Ash gray (Case)

Attached function

Color

[Setting value lock]

[Sensor correction]

[Power failure countermeasure]

The setting data is backed up in non-volatile IC memory.

[Self diagnosis]

The CPU is monitored by a watchdog timer, and when any abnormal status is found on the CPU, the controller is switched to warm-up status with all outputs turned off.

[Automatic cold junction temperature compensation] (Only thermocouple input)

This detects the temperature at the connection terminal between the thermocouple and the instrument and always keeps it on the same status as when the reference junction is located at 0° C (32°F).

[Input burnout indication]

Thermocouple and RTD inputs

If the input value exceeds the Indication range high limit value, the PV display blinks "----", and if the input value exceeds the Indication range low limit value, the PV display blinks "----". If the input value exceeds the Control range, OUT is turned OFF (for DC current output type, OUT low limit value).

| Input | Input ra | inge | Indica | ation rar | nge | Control rar | nge |
|--------------|------------------|---------|------------------|-----------|------------------|---------------|--------|
| КТ | –199.9 to 400.0℃ | | –199.9 to 450.0℃ | | –205.0 to 450.0℃ | | |
| | -199.9 to | 750.0°F | -199. | 9 to 850 | 0.0°F | -209.0 to 8 | 50.0°F |
| | -200 | to | | 250 | to | -250 | to |
| ĸ | 1370℃ | | 1420℃ | | | 1420℃ | |
| IX. | -320 | to | _ | 370 | to | -370 | to |
| | 2500°F | | 2550°F | | | 2550°F | |
| | -200 | to | | 250 | to | -250 | to |
| | 1000℃ | | 1050℃ | | | 1050℃ | |
| 5 | -320 | to | _ | 370 | to | -370 | to |
| | 1800°F | | 1850°F | | | 1850°F | |
| | | 0 to | | -50 | to | -50 | to |
| RS | 1760℃ | | 1810℃ | | | 1810℃ | |
| IX O | | 0 to | | -50 | to | -50 | to |
| | 3200°F | | 3250°F | | | 3250°F | |
| | | 0 to | | -50 | to | -50 | to |
| в | 1820℃ | | 1870℃ | | | 1870℃ | |
| D | | 0 to | | -50 | to | -50 | to |
| | 3300°F | | 3350°F | | | 3350°F | |
| | -200 | to 800℃ | - | 250 to 8 | 850℃ | –250 to | 850℃ |
| E | -320 | to | | 370 | to | -370 | to |
| | 1500°F | | 1550°F | | | 1550°F | |
| | -200 | to | | 250 | to | -250 | to |
| Ν | 1300℃ | | 1350℃ | | | 1350℃ | |
| | -320 | to | _ | 370 | to | -370 | to |
| | 2300°F | | 2350°F | | | 2350°F | |
| | | 0 to | | -50 | to | -50 | to |
| PI -Π | 1390°C | | 1440°C | | | 1440℃ | |
| | | 0 to | | -50 | to | -50 | to |
| | 2500F | | 2550 F | | | 2550F | |
| | | 0 to | | -50 | to | -50 | to |
| C(W/Re5-26) | 2315°C | | 2365°C | | | 2365℃ | |
| 0(111100 20) | | 0 to | | -50 | to | -50 | to |
| | 4200°F | | 4250°F | | | 4250°F | |
| | 199.9 to 8 | 850.0℃ | -199.9 | to 900 | .0°C | -210.0 to 90 | 0.0℃ |
| Pt100 | -200 to | o 850℃ | -2 | 10 to 90 |)0°C | -210 to 9 | 00℃ |
| 1 1100 | -199.9 to 9 | 999.9°F | -199.9 | to 999 | .9°F | -211.0 to 109 | 9.9F |
| | -300 to | 1500°F | -318 | 8 to 160 | 0°F | -318 to 16 | 600°F |
| JPt100 | -199.9 to 5 | 500.0℃ | -199.9 | to 550 | .0℃ | -206.0 to 55 | 0.0℃ |
| | -200 to | o 500℃ | -20 | 06 to 55 | 50°C | –206 to 5 | 50°C |
| | -199.9 to 9 | 900.0°F | -199.9 | to 999 | .9°F | -211.0 to 99 | 9.9°F |

(However, for manual control, it outputs the preset manipulated variable)

| | | | –300 to 900°F | -312 1 | to 1000°F | –312 to 1000°F | • | |
|------|---|--|-------------------------|-------------------|----------------|-----------------------|-------------|--|
| | DC current and voltage inputs | | | | | | | |
| | If the P | If the PV exceeds Indication range high limit value, the PV display blinks "", and | | | | | | |
| | In the F v exceeds the indication range low limit value, the F v display blinks | | | | | | | |
| | maioati | onnango | + Scaling span x 10 | %1 | ng opun x 17 | | | |
| | | | However, if the input | t value exc | eeds the ran | ge –1999 to 9999, | the PV | |
| | | | display blinks " | " or " | "- | | | |
| | Control | range | : [Scaling low limit va | lue – Scali %1 | ng span x 1% | 6] to [Scaling high I | imit value | |
| | DC inpl | ut burnou | t: When DC input is b | urnt out. P | V displav blir | nks " " for 4 t | o 20mA DC | |
| | | | and 1 to 5V DC inpu | uts, and " | " for 0 t | o 1V DC input. | | |
| | | | For 0 to 20mA DC, | 0 to 5V DC | and 0 to 10\ | / DC inputs, the P\ | / display | |
| | | | indicates the corres | ponding va | lue for which | 0mA or 1V is inpu | tted. | |
| | [Burnout] | | | | _ | | | |
| | When th | he thermo | couple or RID input is | s burnt out, | OUT is turne | ed off and PV displa | ay blinks | |
| | " (for DC current output type, OUT low limit value). | | | | | | | |
| | Accessories included: Instruction manual 1 copy | | | | | | m 1 longth | |
| | | v V | When the option Heate | r burnout c | | d. Whe hamess of | n, i lengui | |
| | | v | For rating 5A 10A | 200 | | | 1 niece | |
| | | | For rating 50A | ι, 20Α C | Τ (ΔΚΤ4816) | 1 niece | i piece | |
| | Accessories s | old sena | rately: For DC current | input 500 | shunt resi | stor (ΔΚΤ4811) | 1 niece | |
| | A0003301103 3 | ola sepa | atory. For Do carrent | input, 00 | Shancresi | | i piece | |
| 10.2 | Optional specif | ications | | | | | | |
| | Heater burnou | t alarm | | . . | | | | |
| | Watches the heater current with CT (Current transformer) and detects the burnout. | | | | | | | |
| | When this option is added, this option shares common output with Alarm output and Loop break alarm. | | | | | | | |
| | I his option cannot be applied to DC current output type. | | | | | | | |
| | Rating | : 5A, 10A | A, 20A, 50A (Must be s | specified) | | | | |
| | Setting range | : 5A, 0.0 | to 5.0A (Off when set | to 0.0) | ff | - 0 0) | | |
| | | | | | m when set to | 5 U.U) | | |
| | | | | 20.0A (OII \ | when set to C |).()) () | | |
| | Setting accurac | | of the rated value | | | , | | |
| | | y. <u>-</u> 5% · ∩N/∩⊏ | F action | | | | | |
| | Action | : ON/OF | F action | | | | | |

11. Troubleshooting

Output

: Open collector

Control capacity, 24V DC

If any malfunctions occur, refer to the following items after checking the power supply to the controller. **11.1 Indication**

0.1A (Max.)

| Problem | Presumed cause and solution |
|----------------------------------|---|
| | Sensor (Thermocouple, RTD and DC voltage 0 to 1V DC |
| " is blinking on the PV | input) is burnt out. |
| display. | Change the sensor for new one. |
| | Is the lead wire of the sensor (Thermocouple, RTD and DC |
| | voltage 0 to 1V DC input) securely connected? |
| | Connect it to the input terminal properly. |
| The indication on the PV display | Check if the input signal source for DC voltage (0 to 10V DC) |
| does not change. | and DC current (0 to 20mA DC) is normal. |
| | Is the input signal wire for the DC current (0 to 20mA DC) |
| | and DC voltage 0 to 10V DC securely connected to the input |
| | terminal of this controller? |
| | Connect the sensor lead wire securely to the input terminal |
| | of this controller. |
| "" is blinking on the PV | Check if the input signal source for sensor (DC current |
| display. | "4 to 20mA DC" and DC voltage "1 to 5V DC" input) is |
| | normal. |
| | Is the input signal wire of DC current 4 to 20mA DC and |
| | DC voltage1 to 5V DC securely connected to the terminal |

| | of this instrument? Connect the input signal wire securely to the terminal of the instrument. |
|---|---|
| The indication on the PV display is abnormal or unstable. | Is designation of the sensor (input) correct? Set the correct sensor (input). Is the polarity of the sensor input correct? Wire it correctly. Temperature unit (°C/°F) is mistaken. Set the correct unit. AC may be leaking into the input of this controller from the thermocouple or RTD connected to the measured object. Keep AC from leaking into the input of this controller from the thermocouple or RTD of the measured object. |
| <i>"Eァァ 1</i> " is indicated on the PV display. | Internal memory is defective. Contact our agency or us. |

11.2 Key operation

| Problem | Presumed cause and solution |
|---------------------------------|---|
| Setting values do not change | Lock 1 or Lock 2 is selected in setting value lock selection. |
| even if the 🔺 or 💌 | Cancel the Lock mode. |
| key is | PID auto-tuning is performing. |
| pressed during setting mode | Cancel PID auto-tuning. |
| The setting indication does not | The value of scaling high limit setting or low limit setting in |
| change in the input range even | auxiliary function setting mode 2 may be set at the point the |
| if the 🔺, 💌 keys are | value does not change. |
| pressed, and unable to set the | Set the proper value. |
| value. | |

• If you have any inquiries, please consult our agency or the shop where you purchased the unit.

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